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CONTROL SYSTEM PROGRAMMING REMOTE COMPUTING and DATA DISPLAY

by
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Submitted in partial fulfillment of the requirements for the degree of MASTER OF SCIENCE

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ABSTRACT

The increasing demands upon large digital computing facilities have necessitated the developement and use of a system control program to provide for continuous automatic job processing. A comparative study of two current systems was conducted. The first, CDC FORTRAN 60, is described and its advantages and disadvantages are pointed out. This system was modified by the authors to incorporate a remote (satellite) operation in a time shared mode. The second system studied was the CDC GOOP MONITOR system. This system, a more complex, sophisticated control system is likewise discussed. Modifications to correct certain disadvantages of this system are shown, along with the programming necessary to provide for remote station operation in the COOP MONITOR environment.

Several other programs which were developed by the authors to improve the computing center's capability are documented. These include; (1) A graph plotting routine utilizing CDC 1604/160 computors and a CDC 165 / CalComp Plotter, (2) A large file merg sort routine, and (3) A data display "Line Printer" routine.

The authors wish to express their appreciation to Professor Mitchell L. Cotton of the U.S. Naval Postgraduate School, and to the personnel of the school's computing center for their kind consideration during the term of this thesis.



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ABBREVIATIONS

MCS Master Control System

SCS Secondary Control System

RHT Running Hardware Table

SIO Standard Input Output

AET Available Equipment Table

AEDNT Available Equipment Driver Name Table

RBL Relocatable Binary Loader

ELT Edit Library Tape
PLT Prepare Library Tape
FWA First Word Address

LWA+1 Last Word Address Plus One

I/O Input/Output

BCD Binary Coded Decimal
CDC Control Data Corparation



1.0 INTRODUCTION

At present, the Naval Postgraduate School's computing center utilizes approximately 60% of its prime time processing short, 1 to 15 minute, "job shop", input programs. Practically all of these are of a scientific problem solving nature. Three different compiler/assembler control systems for processing these programs are currently in significant usage. They are the Control Data Corporation's "Fortran 60 System", the Naval Electronics Laboratory's "Neliac Compiler", and the school's own algebraic assembly routine, "Scrap". Of the above, the Fortran 60 System is the only system which incorporates a full control, automatic, job sequencing "monitor" system. Much more will be said about this "monitor" capability and the Fortran 60 System. The remaining 40% of the prime computing time is utilized for class laboratory instruction, maintenance and update of systems library tapes. data retrieval, schedule analysis, and other special job users.

The non-prime time, 1630 to 0800, is scheduled block time for the various developement projects and long run programs.

This environment places increasing demands upon the computing center's capabilites. Not only is improved efficiency required but also more flexibility is in demand as the programmer's talents become more and more sophisticated.

Several tasks were undertaken in the scope of this thesis project. Towards improving over-all system efficiency, a comparative study of the present Fortran 60 System and its proposed successor, "Coop Monitor/Fortran 62 System", was conducted. As a result, an outline and a discussion of the outstanding advantages and disadvantages of each system is incorporated in this thesis.

Towards improved system flexibility, two new facilities were developed. They were the implementation of an operational remote (satellite) computing station and a system's provision for automatic graph plotting of two dimensional computer



derived arrays.

The full implementation of the remote station complex is a continuing group project with much remaining to be accomplished. As an aid to those who pursue this task, several recommendations are made and suggested methods for solving some of the problems are expounded.

Besides the work accomplished in establishing the satellite station, another aspect of the center's services was improved. This was the provision of a graph plotting system. This required the developement of a plotting program for both the Fortran 60 System and a much improved and shorter Grafplot program for the Coop Monitor System. The major portion of this project was completed during the author's five week industrial tour at the Control Data Corporation, Palo Alto, California. The off-line processing of this graph plotting program was provided by rewriting, with many revisions, an existing plot drive program initially developed by the U.S. Naval Fleet Numerical Weather Facility, Monterey, California. Versions of this program were developed to operate on either the 160 or 160A CDC computers. The plotter employed is the CDC model 165/CALCOMP incremental plotter. This system has proven very effective and has enjoyed considerable usage. Although this provided an improved data output medium for the center, it has also stimulated an increased interest in utilizing the Digital Computer for project studies. Thus the center's task and effectiveness is ever increasing.

A second method of data display was provided by utilizing a new cathode ray tube, Data Display model DD65, as an "on-line" line printer. Thus it is possible to monitor the Fortran System's output listings concurrently as it is listed upon the magnetic tapes for later off-line hard copy printing.



This is a small programmed package to demonstrate a unique method of providing a "rolling page" effect on the display tube. The details of the technique are explained in section 4. It was originally planned to provide much more programming for the data display unit, however, the unexpected complexity of the Coop Monitor System limited the extent to which the authors were able to pursue this task. Modifications to the Coop Monitor System were made to couple the data display to the system. If time permits before termination of this work, the display driver routines will be completed to provide normal input/output capability between the display and the central processing computer.

Two additional projects of secondary importance were completed. They were the provision of tape control programs to enable utilization of the 1607 magnetic tape units by the CDC 160 computers when assembling programs using the CDC 160 OSAS Assembly System. The other project was the development of a merg sort routine for large files written in 120 character BCD format. This sorting capability was a very desireable ability which had not previously been available at this installation.



2.0 FORTRAN 60 SYSTEM

The Fortran 60 System is the present fortran processor in use at the Postgraduate School. It is maintained on a system library tape, recorded in binary format, 54 words per record, see ref.21. The records are grouped sequentually such that one record or several records may constitute a program package. These packages are referred to as being "subroutines". The first such package on the system library tape is the System Control Routine and is titled "Resident". Operation of the system is as illustrated by figure 1. The figure points out the control transfer sequence which takes place after the resident program is "bootstrapped" into the 1604 computer's memory. A short verbal explanation of the diagram follows: Initial "bootstrap" procedures are executed by the operator. This reads in the Resident program from the system library. The resident program then assumes control of the computer.

2.1 Program Control

The section of resident in which control normally resides is termed "Program Control". The function of program control is to interpret control instructions which will direct the transfer of control to some secondary control package or subroutine. All such routines must eventually return control to "Program Control". Normally program control reads its instructions from the console typewriter. These control statements may be any one of the twenty routine names shown by figure 1, or one of the eight transient program names which previously may have been "called" into core (memory) by the call routine. Some of the twenty control statements have arguments. The CDC Fortran System Manual and its update revision notices



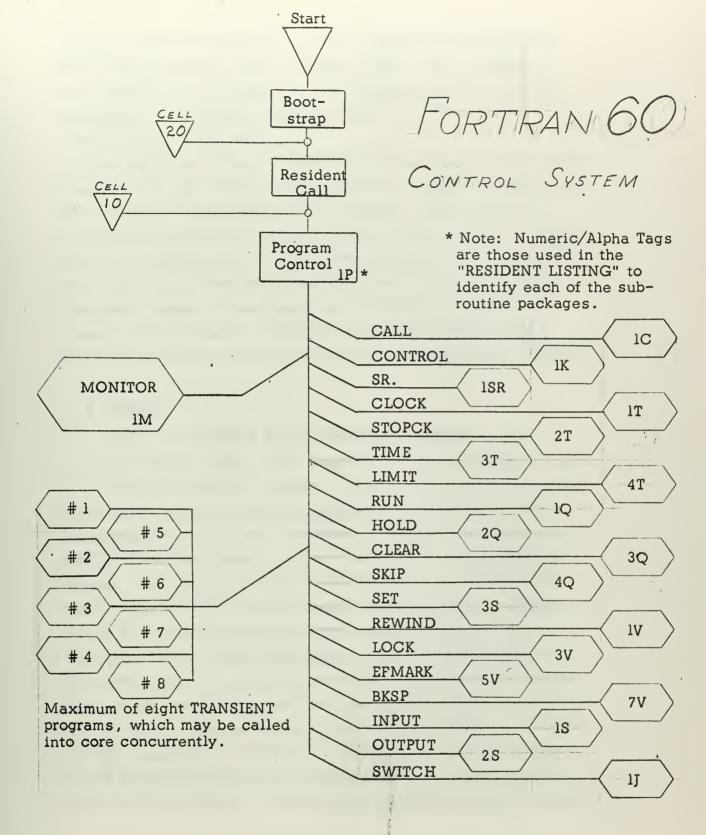


Figure 1



discuss the use of these arguments and control statements, with the exception of the statement "SR". This statement was added by the authors to provide automatic call of eight frequently used service routines such as transfer, vfylib, list, copys, verify, etc.

As mentioned before, normal operation of the control system requires that all sub-program packages, to which control may be transferred, must provide for returning control back to Program Control at the end of the directed processing sequence. Thus an examination of the resident programming, appendix IV, will find that it consists of several small programming sub-routines. Some of these are self contained and some are linked to other routines which assist in the performance of the functional task for which each basic package was designed.

2.2 Monitor

It has been pointed out that "Program Control" has a very responsible task in the organization of the system, since it is the prime control routine. The next most important and the largest of the programming packages in resident is the processor for the control statement, "Monitor" or sometimes called "Monitor Control". It is a routine to which program control can transfer control of the computer to provide automatic processing of stacked input Fortran Programs. Monitor is by far the most complex of the resident routines and yet, compared to the second generation system, Coop Monitor, it is rather simple. A full understanding of the monitor routine is best obtained by reading this section of coding in appendix IV. Briefly, operation of the monitor is as follows. Program Control receives a statement, "Monitor, 3, 4." This statement could have had up to seven arguments, but for this example two will be sufficient. This statement directs program control



to transfer the arguments into the monitor control routine and then to transfer control to monitor. Monitor then tests certain flags to check if recovering from a previous job execution which lost control, requiring a forced recovery entry back to monitor. This not being the case, monitor then reginds all output mediums, senses for input/output conflicts, initilizes for next library routine call, builds a tape assignment table, reads from the input medium (tape 3 in this example) detects a job description record, calls in the Fortran compiler, inserts the necessary arguments into the compiler, then transfers control to the compiler for compilation of the input program. If the program is successfully compiled, control is returned to monitor and monitor then transfers control to the program just compiled, this is termed "executing the program". If the program is successfully executed, it returns control back to the monitor which then returns to process the next job on the stacked input medium.

2.3 Resident Routines

The technique of transferring control of the computer has been demonstrated and we should now discuss a technique of utilizing the resident routines which are available to non-resident programs. The organization of the system provides what are called "low core" (cells 7 thru 35), entry points. These entry points are assigned to be the permanent entries to several of the programming packages contained in resident. All of these entries are shown in figure 2. Since these cells are permanently assigned, standardization limits all usage of the resident routines by non-resident programs to enter via the appropriate low-core cell. This then allows modifications to be made on the system's "Resident" routine without influencing the non-resident routines. As illustrated by



figure 2, eight of the low-core entry routines have switches which condition on whether monitor is controlling the job sequencing. If the monitor is in effect, then these eight entries are diverted in order to trap illegal monitor usage of input/output units.

The low-core entry routines are rather self explainatory. They are mostly service routines such as read, write, equipment controllers, and message handlers.

Nearly all the routines in resident fall into one of the two groups discussed. There are a few which are not in either group. These shall now be discussed.

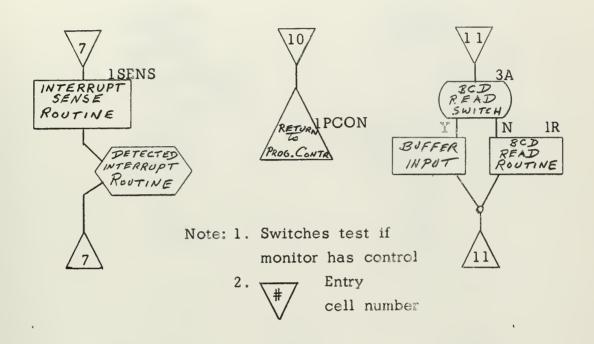
Two similar routines which have not been mentioned are the "Input Index Register Loader" and the "Output Index Register Loader" routines. These two serve to translate the alphabetical equipment designators into the equipment codes as listed on the first page of the "Resident List", appendix IV. These equipment codes are then loaded into index registers #1 and #2. The index registers then control the proper equipment selection for the read/write routines.

Two other routines are the "Tape Read/Write" routines. These are both tape drive routines for controlling the system's magnetic tape units. The routines are commoly used by both the BCD and Binary Read/Write routines. The tape drive routines apparently were the only equipment drivers deemed worthy of individual programming. All other equipment drivers are embedded into the main body of the Read/Write routines.

There is a routine called, "Initialize for Next Call". Its function is to reset the program bias and program counter cells, #62 and #63 respectively, prior to calling each program from the library tape. This routine is bypassed if



"LOW CORE", CELLS 7 THRU 33
RESIDENT ROUTINE ENTRIES
WHICH ARE AVAILABLE TO
NON-RESIDENT PROGRAMS



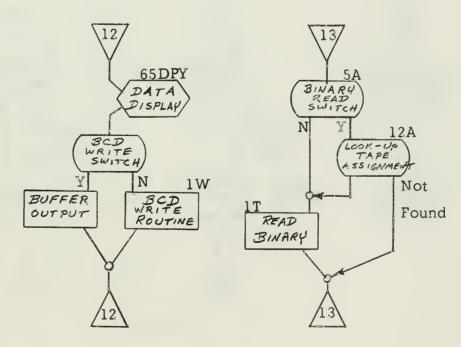
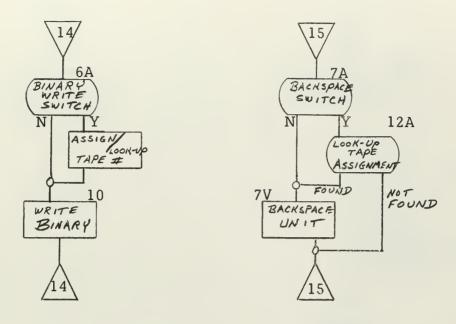


Figure 2 a





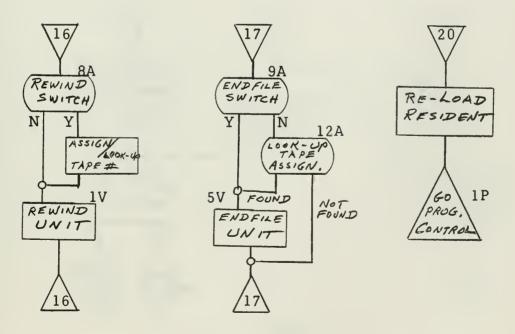


Figure 2b



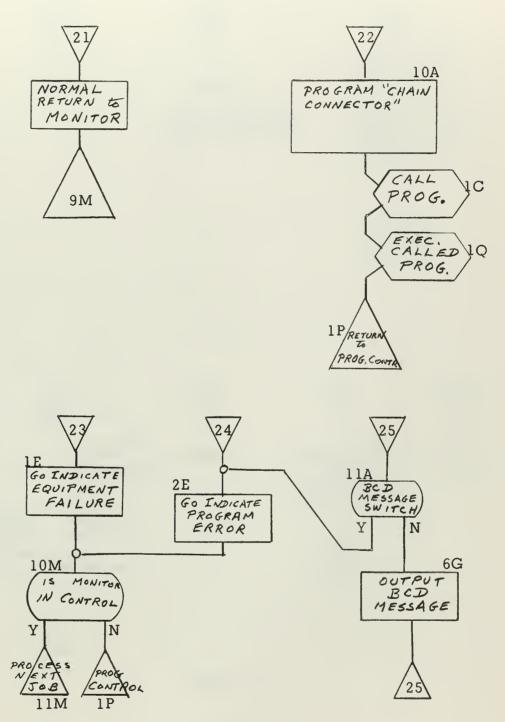
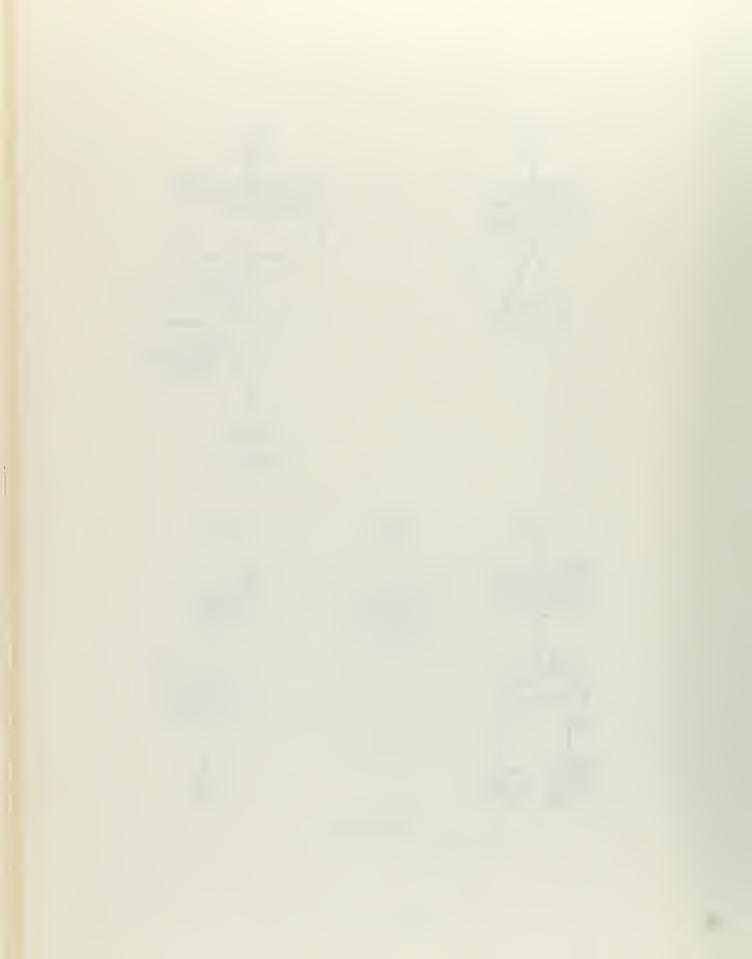
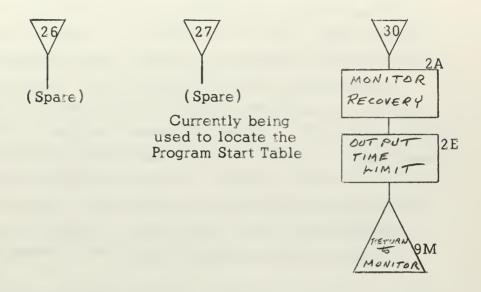


Figure 2c





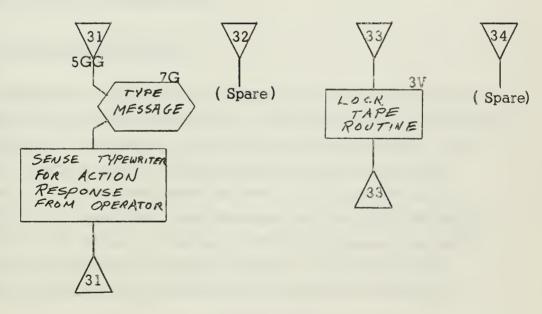


Figure 2d



a "Hold" control statement was issued immediately prior to the issue of the "Call" statement.

One final routine to be discussed is the low-core cell #22 entry routine, "Chain". Its purpose is to call a named program from a designated library medium, then execute it without packing any arguments. This provides a method of segmenting a program which is too large to fit into the available core memory along with its "Common Storage Data Arrays". Thus the segments can be called into core one at a time for execution. Each segment over-writes the previous segment. Processed data from one segment to the next is inter-changed via designated common storage. This idea is extended one step further in the COOP MONITOR system by providing both segmenting and over-lay modes of operation.

The remaining resident routines, which were added to resident by the authors, shall be discussed in section 4.2 and section 4.4. These sections concern the "Data Display Programming" and the "Satellite Station Programming".

2.4 System Characteristics

Perhaps the most significant characteristic of the Fortran 60 System is that in its original form, its Resident control programming including all equipment control, job sequencing monitor, and basic service routines occupied only 4000 octal cells of core storage. The next most important feature of the system is its simplicity of organiztion when compared with the COOP MONITOR system. This is due, of course, to its limited scope. For some uses this simplicity is of great importance. Later the COOP MONITOR system will be discussed, at that time we shall see



that it has many advantages over the simplier Fortran 60 System. With this comparison to make, it is necessary to list the relative advantages and disadvantages of the Fortran 60 System.

2.4.1 Advantages

- a. SIZE; As mentioned, the basic control programming was a modest 4000 octal cells. The authors' additional programming to provide a remote satellite computing station, and cathode ray tube data display facility increased the resident size to only 5000 octal cells. This remains a fairly acceptable figure.
- b. FAST STACKED JOB PROCESS TIME; The Fortran 60 monitor operates in a mode which allows re-use of the Fortran Compiler by many different jobs. This saves library reference time and hence saves process time, provided the compiler remains undamaged. The compiler compiles in memory only and uses no scratch tapes, this also leds to a very fast compilation. There are disadvantages to both these techniques which over shadow the advantages. These will be discussed as listed disadvantages.
- c. MINIMUM INPUT / OUTPUT UNITS REQUIRED; It is possible to operate the Fortran 60 System with only three I/O units operating. This can be a big advantage when several I/O units are inoperative or are assigned for utilization by the center's 160 computers.
- d. OPERATOR SERVICE ROUTINES; A well developed repertoire of operator service routines are an important advantage to a system. Fortran 60 has several such routines such as; endfile mark tapes, rewind, lock, duplicate tape, verify, list, etc. Given a little time, the COOP MONITOR System will probable incorporate several of these routines.



- e. OPERATOR TRAINING TIME; At the Postgraduate School many students are given instruction, check-out, and direct access to the school's computers. As many as 250 students may participate in these laboratory periods per year. Fortran 60, with its simplicity provides a good vehicle for instructional purposes.
- f. MONITOR / OPERATOR REQUIREMENTS; The Fortran 60 monitor system requires a minimum of operator intervention to process a stacked job run. Unless one of the jobs "blows the system Off-Line", ie; manages to execute a storage or jump instruction erroneously, the system requires no operator assists. The COOP MONITOR requires considerable operator manipulation of "Jump Keys" and loading / unloading of tapes, etc. Thus the Fortran 60 System normally requires less operator supervision.
- g. LIBRARY MAINTENANCE; Library maintenance and updating should not be a daily occurance, however it is required frequently. Therefore a quick and reliable system to accomplish this task is required. Fortran 60 has three routines and a simple organization which make this an easy job. The routines are; transfer, vfylib, and list. In contrast, the COOP MONITOR System's "Libedit" routine is rather complex, is indirect via punched cards, and requires apriori knowledge concerning the current "directory" of routines on the library. It would be nice, if a directory dump routine was written and also an individual routine verify capability is required.
- h. MIXED FORTRAN and SYMBOLIC STATEMENTS; Fortran 60 incorporates a fortran compatible symbolic language. Programs written for this system can inter-mix both symbolic and fortran statements on a line for line bases, if desired. For many uses such as programming shifts, logical and masking operations, searches, and other computer operations which the Fortran 60 language doesn't provide, this ability has a distinct advantage.



i. INTERRUPT ROUTINE USAGE; The only usage of the interrupt routine in the Fortran 60 System is for providing a real time clock. This would appear to be a gross neglect of such a powerful equipment capability. The advantage, here, is that the provision for a satellite station operation requires much usage of this interrupt routine, hence having a system which doesn't utilize the interrupt in some complex manner is unique.

2.4.2 Disadvantages

- a. COMPILER VULNERABILITY; As mentioned under advantages, the Fortran 60 compiler is normally called into the computer's memory only when initializing monitor processing of a stacked job run. Thus there exists the possibility that one of the individual jobs may possibly damage the compiler. There after the remaining jobs of the stack are forced to be compiled by a compiler which is no longer reliable. This can result in significant loss of computer and programmer's time, since the programmer is led to believe his program was incorrect.
- b. SLOW TAPE HANDLING TECHNIQUES; Two standard length tape records are employed. Standard binary records are 54 words long. Standard BCD records are 15 words long, thus providing for 120 character records. This standardization is an advantage in some instances. However, the disadvantage is the cost in time which must be paid since the tape motion must be stopped and started between each record. The COOP MONITOR System solved this problem quite well. A second detriment to tape handling is the lack of utilizing the buffer input / output channels to advantage. The only usage of the buffer capability is employed under monitor process control. In this instance, very poor usage is made since there is a complete disregard for error checking during input / output operations. This slow tape handling characteristic is a serious



one since much time is spent by the system in searching the library tape. The library tape can grow to be of considerable length due to the considerations discussed as a disadvantage due to "Multiplicity of Subroutines on the Library". COOP MONITOR solved this problem by providing long variable length library records and a directory which prevents searching the full length of the library tape for routines which are "not available".

- c. PROGRAM SIZE LIMITATIONS; Since Fortran 60 doesn't utilize scratch tapes during compilation, it requires that memory must hold the resident program (4000) plus the compiler (14000) plus the compiled version of the user's program plus an undefined number of cells outside the compiler which are used by the compiler for tables and temporary storage. Thus the programmer losses at least 20,000 octal cells. This is a serious limitation in many large programs. COOP MONITOR has improved this situation, but at a considerable cost in speed, due to the necessity of reloading the compiler for each job and also having to provide an intermediate and "Load and Go" tape.
- d. INEFFICIENT SPACE COMPILATION; Fortran 60 compiles the full size of arrays and reserved space into the binary object program (ie. card images corresponding to the compiled program) at compile time. This coupled with the compilation limitation mentioned previously tends to further hinder efficient usage of memory space during compilation of programs. One advantage this does provide is that arrays and reserved spaces are initially cleared in a Fortran 60 program. This is not true of a COOP MONITOR compiled program.



- e. MULTIPICITY of SUBROUTINES on the LIBRARY; Fortran 60 requires that all subroutines called by a program be available at compile time. The reason for this is that they are embedded into the compiled program as it is compiled. If this compiled program is then added to the library, the library is unnecessarily length—ened. This is due to the fact that versions of the existing sub-routines are embedded in many programs. Not only does this scheme of compilation lengthen the library tape and thereby slow the system down, but it also creates very serious library maintenance problems. Thus the simple corrections or updating of a subroutine isn't so simple anymore. In order to correct a subroutine, it is necessary to re-compile all programs which use the subroutine. This is due to the embedding effect. This can get to be a big bookkeeping problem and can create a lot of work. Again the COOP MONITOR System has solved this problem.
- f. NO PROVISIONS FOR MIXED BINARY / BCD INPUT PROGRAMS; Fortran 60 does not provide any method for inputting a binary program or subroutine into a stacked monitor run, if it is not already a part of the library. Thus no mixed input to the system is allowed. This requires frequent recompilation of subroutines and programs which are not incorporated onto the library tape. Again the COOP MONITOR / FORTRAN 62 System provides the solution.
- g. LIMITED "DE-BUGGING" AIDS; The only automatic debugging aids incorporated into the Fortran 60 System are the compiler and arithmetic error print-outs. The selectable aids consist of a "Map Language" (see ref. #21, pg #102) listing of the compiled program, and a few dump routines which were never very effective. A magnitude improvement has been made by the COOP MONITOR System towards providing de-bugging facilities, both automatic and optional.



- h. UNDESIRABLE INTERMEDIATE LANGUAGE FORMAT; The intermediate language of the Fortran 60 compiler is "Map Language". This form of computer coding can become familiar, but only a small percentage of the general users of the computer facility were ever motivated to use it. Three "languages" for coding a single compiler seems to be more than should be required. Successful utilization of the Fortran 60 System requires a knowledge of the fortran language, CDC Symbolic format, and of the intermediate language, "Map". The Fortran 62 system is a two language system and is quite acceptable except for the exclussion of the line for line inter-mix capability between fortran and symbolic coding.
- i. POOR INPUT / OUTPUT FLEXIBILITY UNDER MONITOR CONTROL; The Fortran 60 System originally had a very weak tape assignment system. It would assign tapes for scratch when the units weren't even loaded. This was corrected by the authors for the school's facility. Another deficiency is the inability of the monitor to provide multiple input / output BCD units. This is desired in many programs, for instance, when cumulative data is being generated and processed over a long period, or when special table lists are to be formed by a program, etc.
- j. SLOW CARD READ / PUNCH ABILITY; The school's "On-Line" card facility is a CDC 1609 system which is capable of operating at either 50 or 100 cards per minute. The Fortran 60 system provided operation only at the 50 card per minute rate. COOP MONITOR will run at the maximum speed of 100 cards per minute and compiles as it reads if the card reader is being used for input. This rate is still too slow for a general usage on-line input medium, hence it is used only as a back-up system for the IBM 1401 System which normally processes the card to tape conversion "off-line".



3.0 COOP MONITOR SYSTEM

The COOP MONITOR SYSTEM was developed to allow a computer facility the ability to operate with only one "library" tape and yet effectively process any type of input programming or source language. This would eliminate the need to sort incoming jobs into separate groups to be run under individual library tapes. The advantage of a single library is readily apparent when operation from a remote station is anticipated, where the operator is physically separated from the main computer and unable to change the current system library tape.

To increase COOP MONITOR'S flexability it is organized into two basic levels of control. At the highest level is the Master Control System (MCS), which maintains the overall system coordination and supervision. At the next level is the Secondary Control System (SCS), and there may be any number of these available on the library. Each SCS is designed to perform a particular job or combination of jobs depending on the requirements of the computer facility.

A brief description will now be given covering the basic organization and operation of COOP MONITOR, for a more detailed description refer to ref.10.

3.1 <u>Master Control System</u>

To accomplish the desired system supervision, MCS is organized into nine functional subroutines and the Bootstrap loader (BOOT), see figure 3. BOOT and the first eight subroutines make up the "permanent" resident, with the memory space occupied by the Job Sequencer (6000 cells) released for use each time control is given to the Secondary Control System. After the SCS has finished using the subroutine



- "Loader" the memory space it occupied may also be released for use by the current program. This procedure allows MCS to be very large and complex (13500 cells) and yet not unduly penalize an input program in memory space requirements. The basic functions of each subroutine are as follows:
- a. BOOT; Contains the Available Equipment Table (AET), which enables MCS to determine the input/output units available to the computer and their intended use. This routine will load on option either MCS or the system recovery dump routine "EXTREC". BOOT also contains the MCS flags to store current job information to allow intra-job continuity.
- b. CLOCK; Allows use of the computer real time clock to set a time limit on the current job. This routine is available to the programmer to set one additional time limit and also may be used to determine elapsed time.
- c. MEMREC; Maintains a record of the limits on the one contiguous block of available memory between resident and any programs loaded into high core.
- d. OPCON; All communication between the computer operator and MCS or SCS is thru this routine. This input or output is normally via the console typewriter.
- e. INTERRUPT; This routine has three sections, SELECT, DETECT, and REMOVE. These allow for the selection and detection, or the release of any of the internal computer interrupts or on channels 1 to 6 inactive.



- f. READ/WRITE; This subroutine controls <u>all</u> input/output operations of the computer. Provides protection from illegal use of any unit and prevents interference between units on the same channel.
- g. ERROR; Used in the event of user program failure or the detection of illegal operation by MCS, entry into this subroutine will terminate the current job. ERROR will output the current contents of all the console registers (on the standard output medium) and the lower address of cell 7, and then determine if the user desires a memory dump.
- h. RW1607; The driver for the magnetic tape units and the only driver contained within MCS. This subroutine is the only place where tape units are selected and activated, except in BOOT for loading MCS or EXTREC.
- i. LOADER; Loads <u>all</u> relocatable binary programs or sub-routines either from the system library or user provided input medium. This subroutine packs programs into high core memory with common block storage assigned to low core just following "LOADER".
- j. JOB SEQUENCER; Used between input jobs to set program limits, determine and load input/output drivers requested by the user, and to call and transfer control to the desired Secondary Control System (SCS). This subroutine also contains the programming to process any computer operator statements received via "OPCON".

These functional blocks are closed subroutines with multiple entry points depending on the particular function desired. These entry points are available to all routines and <u>must</u> be used whenever one of the above operations is necessary. This also includes other blocks within MCS, example, The JOB SEQUENCER



BLOCK DIAGRAM COOP MONITOR

MCS EXTREC BOOT BOOT (AET) (AET) CLOCK RECOVERY DUMP ROUTINE **MEMREC** RW1607 OPCON SELECT PRINTER DETECT **REMOVE** READ WRITE READ WRITE TYPEI/O ERROR **JCLNUP** RW1607 LOADER (AEDNT) JOB S E Q U E N C E R



must use LOADER to make a library call, and LOADER in turn must use RW1607 to actuate and read the magnetic tape unit. These subroutines operating together as a Master Control System provide the following features:

- a. Automatic, variable job, sequencing, including accounting records and time and output line limits set for each job.
- b. Operator-Machine communication.
- c. Assignment of all input/output units and the loading of the necessary drivers for these units.
- d. Single linkage to all input/output drivers to protect them from interference and illegal use.
- e. Flexible linkage to the CDC 1604 interrupt features.
- f. Automatic recovery features in the event of "user" program failure.
- g. Calling and transfer of control to any desired Secondary Control System (SCS).

The assignment and control of input/output equipment by the MCS is accomplished thru three tables. The first, the Available Equipment Table (AET), lists all the input/output equipment connected to the computer. Some of these I/O units are designated as "standard" (SIO), and are assumed to be always available for use by the system. The entries in the AET (one for each I/O unit), contain the following information: Allowed use, current job assignment, standard unit or not, equipment type, and the location of the I/O driver name. For



a complete description of the AET entry format see ref.10. This table is set for each installation and is changed only as equipment status changes. A listing of the current AET is shown in figure 6c.

The second, the Available Equipment Driver Name Table (AEDNT), lists the name and entry point location for each I/O driver subroutine for controlling the units listed in the AET. The entries are two words long. The first word contains the entry point locations of the routine if it is in memory, or an exit to MCS if not in memory, see section 3.5 part D for an example of an AEDNT entry.

The third, the Running Hardware Table (RHT), lists the input/output assignments of units for the current job only. The entries are AET entries with the address of the proper driver entry point inserted and the allowed use set. Logical unit numbers are used as an index to this table, logical numbers 1-49 are available to the programmer, 0 is reserved for the system library tape and 50-63 for standard units.

3.2 <u>Secondary Control Systems</u>

The great flexibility possible with the COOP MONITOR is in the use of a Secondary Control System (SCS) to control the processing of a specific job. There can be any number of Secondary Conrol Systems which may be written by each computer facility to handle the specialized needs of its users. Thus for use at the Postgraduate School the standard "stacked job" daily production runs would be controlled by one SCS, and a satellite digital controller simulation by a different SCS, and a real time radar intercept problem by a third SCS. All of these SCS would be placed on the standard library tape and available within a few seconds after a particular one is called from the library. No modification is needed in the standard COOP MONITOR



to use a different SCS. The name of the desired SCS is given to the JOB SEQUENCER in MCS at the begining of each job and this name will go to LOADER and the SCS will be loaded from the system library.

There are two SCS provided in the present version of COOP MONITOR, these are called "COOP" and "LIBEDIT". A brief description of each is given to illustrate the technique of tailoring a SCS to do a specific problem. The first, COOP, is responsible for the intra-job sequencing necessary to compile and execute an input job, ie; the calling of compilers or assemblers, transferring binary card images to a "load and go" tape, calling LOADER to load the "load and go" tape and finally, execute the loaded program. The present version of COOP can call two compilers, FORTRAN-62 and CODAP1 (actually an assembler), but COOP can be modified to accept any number of compiler languages. COOP also contains internal routines for user controled binary deck manipulation, loading and execution.

The second, LIBEDIT, has two subroutines, Edit Library Tape (ELT) and Prepare Library Tape (PLT). Edit Library Tape is used for minor changes in the system library such as a deletion or addition to the subroutine file or within MCS and EXTREC. This secondary control system makes a copy of the present library tape upto the point of the desired change and then inserts or deletes the proper information. For a detailed description of the steps necessary in a complete LIBEDIT, see appendix I and ref.17. Prepare Library Tape is used for major changes to the system library. The user must now supply all the information necessary to produce a new version of the system library tape, nothing is copied from the old library tape. LIBEDIT does not provide any means of verifying the portions of the new library tape that were not changed.



3.3 System Operation

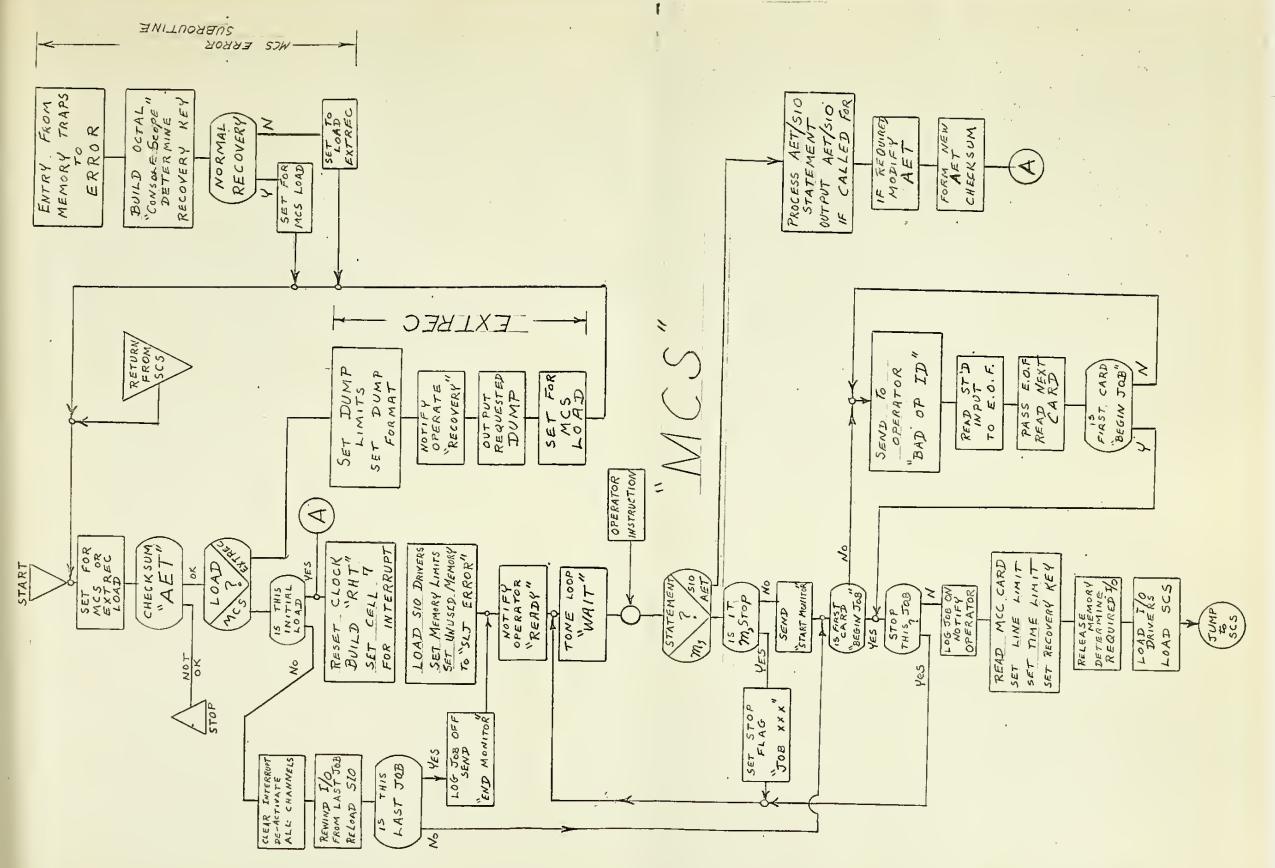
A brief description of the operation of MCS can now be given, for a more detailed description see ref. 10. The first record of the library tape, BOOT, see figure 4, is read into the computer by manually selecting and activating the proper magnetic tape unit. BOOT is then executed at cell #2, see figure 6, and will verify the AET table and then skip over the next record on the library tape, EXTREC, and load MCS, see figure 4. Control is now given to MCS which determines the standard input/output units (SIO), loads the necessary drivers for those units if they are not in memory, fills the unused memory space with a jump to ERROR instruction to trap user program failures, and then notifies the computer operator the system is ready to accept job assignments. operator then either signals MCS to alter the AET or SIO assignments or to begin processing the "stacked job" on the standard input. When signalled to begin processing, MCS reads the control card from the standard input, logs the first job on the standard outputs (list and punch tapes and the console typewriter), and sets the time and output line limits for the current job, the recovery key is stored in BOOT. The input/output units needed, in addition to the standard units, by the incoming job are determined and assigned and if the proper drivers are not already in memory they are called and loaded. MCS then releases the memory space occupied by the non-permanent section of MCS (Job Sequencer) for use by the SCS or the input program. The desired secondary control system is determined and loaded into memory and MCS then transfers control to this SCS, see figure 5. When the SCS has finished processing the current job, control is returned to BOOT with an indication for a "normal" or "abnormal" job termination. For a "normal" termination BOOT reloads MCS



COOP MONITOR LIBRARY TAPE FORMAT

	Tape Load Point
BOOT	
EOR	End of Record Gap
EXTREC	Extended Recovery
EOR	
MCS	Master Control System
EOF	First End of File
DIRECTRY	Library Directory
EOR	
FIRST SUBROUTINE	
EOR	
SECOND SUBROUTINE	
EOR	
THIRD	
SUBROUTINE	
EOR	
28	To Second End of File
	Figure 4





COOP MONITOR SYSTEM MCS
FLOW DIAGRAM
Figure 5



and if there are more jobs on the standard input, the cycle is repeated. For a "abnormal" (error) termination a "Console Scoop" (the contents of all the console registers) is prepared and sent to the standard output tape to aid the programmer in debugging efforts. The recovery key, set by the user at the start of the job, is examined to determine of a memory dump is desired, if not control is given back to BOOT for a MCS reload and the process continues as before. When a memory dump is desired control is returned to BOOT for a EXTREC load, see figure 6. Extended recovery then provides the desired memory dump on the standard output tape and returns to BOOT for a MCS reload. Again if there are more jobs on the standard input tape MCS will start the sequence over, otherwise it will terminate this run and notify the computer operator.

3.4 System's Characteristics

Once over the initial shock of working on a system of this size, the next effort was to consider COOP MONITOR'S good and bad characteristics when the special requirements of the Postgraduate School computer center were included in the system. These special requirements included the daily "stacked job" production runs of short duration, longer runs by the students during the evening, the increased use of the satellite capability of the schools computers, and the addition of a sophisticated digital display unit (Data Display Inc. DD65) as a remote computer input/output device. In this light the COOP MONITOR was determined to have the following major advantages and disadvantages:

3.4.1 Avantages

1. The system can handle stacked input jobs written for multiple compiler languages. The present version includes Fortran-62 and Codapl and the addition of the Neliac compiler and the Scrap assembler is possible.



- 2. Operates with multiple secondary control systems each specifically designed for a job. Present system has two, COOP and LIBEDIT and others may be added to process satellite and remote display problems.
- 3. Automatic, programmer controlled, debugging aids such as the "console scoop", provided in the event of program failure and the "snap" feature for those that do not fail but also do not produce correct results.
- 4. Automatic system recovery in the event of failure by the input program.
- 5. All input/output is thru one routine, therefore it is very difficult for an input program to illegally use any I/O unit. Interference between units is also minimized.
- 6. COOP can accept mixed, binary and source language, input programs.
- 7. Magnetic tape driver routine uses variable block read and write for maximum speed when controlling the system library tape. All read/write is buffered, with parity and length checking.
- 8. Variable standard input/output units are allowed and these can be changed before each job.
- 9. Multiple input/output units for each job are allowed up to the maximum available to the computer.
- 10. The system is capable of handling very large input programs as MCS releases memory and the compiler used is over written when the program is loaded for execution. For programs that are still too large, segmenting and overlaying are provided.



- 11. The compiler used, Fortran-62, has special features all its own; easy to read intermediate language (Codapl), buffer operation for input/output, and single library subroutine call for each program.
- 12. Compiler is reloaded for each job thus assuring a clean start.
- 13. The system will accept Fortran-63 when it is available.

3.4.2 Disadvantages

- 1. The system is very large (13500 cells) and complex, making it difficult to gain the understanding necessary to perform any system modifications.
- 2. Many complex (at first) control cards are necessary to process each input job.
- 3. Provides an unused and unsuppressable accounting information output on the paper tape punch.
- 4. Normal system operation requires a large number of standard input/output units to be operating. Four magnetic tape units (library, punch, input, and output), the paper tape punch for system accounting, and the console typewriter are required to satisfy the "standard" I/O requirements.
- 5. Inability of the computer operator to add or delete a standard input/output unit (the type of I/O unit can be changed).
- 6. Step by step operation by the computer operator via the console typewriter is not possible.



- 7. The interrupt schedule is not compatable with a real time problem solution in a micro-second time sharing mode, due to the frequent use of interrupt lockout. No provision is made for operation from a remote (satellite) station.
- 8. No programmed restart available for use by non-autoload CDC 1604 computers (the autoload must be simulated by manually performing the required instructions).
- 9. No operator service routines are available such as call, copy, transfer, verify, etc.
- 10. Program errors are sent only to the standard output tape requiring the user to list this tape before determining any errors.
- 11. The system would not output/input on the CDC 1609 card punch/read unit available at the computer facility.

3.5 Alterations To Coop Monitor System

After a basic understanding of the Coop Monitor System was obtained, it became apparent some modifications would be required before the system would be acceptable for operation at the Postgraduate School's computer facility.

The first modification attempted was the alteration and corrections needed in the cardread and cardpunch drivers to allow operation with the CDC 1609 card read/punch unit. In addition to the corrections, it was also necessary to rewire the unit's plugboard to make the read/punch format compatible with the Coop Monitor. These read/punch routines are an improvement in speed to 100 cards per minute vice the 50 cards per minute available with Fortran-60. Once the drivers were corrected, they were recompiled and the binary versions



were added to the system library tape using the secondary control system "LIBEDIT". For a complete description of the LIBEDIT procedure, and the input job format see appendix I. The correction of these subroutines provided a library tape more suited to the needs of the school computer center but still left some major deficiencies in the system that would prevent convenient operation. These were the following:

- a. The unsuppresable accounting medium being output on the paper tape punch, requiring the punch to be selected at all times. This made the paper punch unavailable to the user as an output device.
- b. No provision for a programmed restart for operation on a non-autoload computer (CDC 1604). In the event of MCS failure a manual "bootstrap" is required.
- c. Error messages from MCS "LOADER" are not available to the user except by listing the standard output medium.
- d. No provision for handling operation from a remote station. The correction of these deficiencies all had one thing in common, they would all involve changes within the structure of MCS. Many early failures soon made it apparent changes in MCS could not be made without a complete understanding of the internal organization of MCS, and a positive knowledge of the operation of LIBEDIT. After these two programs were more thoroughly understood, the modifications resulted in the successful production of a new library tape providing these
- a. Accounting medium suppressed, the paper tape punch is not selected unless the operator intends to use it as an output medium.

new features:

b. A programmed restart is available, at cell #30, and this will simulate the "autoload" feature of the CDC 1604A except for the initial load.



- c. All error messages from MCS "LOADER" are now also output on the comment to the operator medium, normally the console typewriter.
- d. All linkages necessary (AET and AEDNT entries) for the calling and execution of a driver subroutine for the remote display (DD65) are now in MCS. Space required for this driver is reserved (1000 cells) within the "permanent" section of MCS just prior to LOADER.

These modifications now provide a library tape that should be much more convenient for the computer center to use and at the same time provide a system that will readily accept experimental drivers and subroutines for operation from the remote station. The detailed explanations and coding involved in these modifications are shown in the following sub-sections.

A. Modifications to BOOT

The postgraduate schools computer (CDC 1604) is a non autoload machine and thus requires a manual selection and activation to read the library tape. The COOP MONITOR uses the autoload feature anytime there is a failure of the automatic recovery routine. To avoid the necessity of this manual "bootstrap" each time this may occur a simulated autoload was placed into BOOT starting at cell #30. This allows an "autoload" restart when needed. At the same time the standard input/output assignments in the Available Equipment Table (AET) were altered to provide the following:

- a. Library on channel 3/4, tape unit #1
- b. Input on channel 3/4, tape unit #2
- c. Available for use, channel 3/4, tape units #3 and #4
- d. Output on channel 5/6, tape unit #1
- e. Punch on channel 5/6, tape unit #2
- f. Scratch 1 and 2 on channel 5/6, tape units #3 and #4



9

AGE

```
BUFFER
                                                                                 ERMINATE
                                                                           ×
                                                                           HECKSUM-9
HECKSUM
                                                                                 000
       BOOT
                                                                                 ŏ
                                                                                 M
       IDENT
                                                                          WA+1
         1
             F WA
                                                                        \overline{\omega}
                                                                        \sum
                                                                           -00M
                                                                        SY
ART MONITOR RUN.
GIN JOB 231
OP,,,S/25,20,50000.
DAP1,1,1,
                                                                           45000
            POINTS
                                                                        NO EXTERNAL
                                                                           00002
                                                                               00003
           ENTRY
        RANGE
-WOO
```

Secon



CCCUMULATE CHECKSUM ET ARITHMET UMP IF SW 1 I UMP IF SW 1 I UMP IF SW 1 I CCUMULATE CHECKSUM	AUTO LOAD ENTRY WAIT READ IN BOOT WAIT JUMP TO BOOT	SYSTEM LIBRARY
X X E C U X C U X E C U	320158 3 2 20008 7 320008 -0	0 132018
C C C C C C C C C C C C C C C C C C C	COLXXXX	31
00000000000000000000000000000000000000	74440000000000000000000000000000000000	1 0 1320
	00030 00031 00032 00033	00034



AVAILABLE AVAILABLE STANDARD OUTPUT STANDARD PUNCH SCRATCH 1 SCRATCH 2 1609 PRIMARY READ 1610-1-PUNCH INPUT FROM DISPLAY TYPEWRITER INPUT COMMENT PTP PTR PTR PTR PTR PTR PTR PTR PTR PT
0 2820NT#1 0 5820NT#1 0 5820NT#1 1 5820NT#1 1 5850NT#1 1 0 5850NT#1 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
AETEND CHECKSUM JSFLAG SIEDF LINECNT JOBXXX JSTOPX RDATA
00140000000 000000000000000000000000000
000000-0-000000000000000000000000000000
000000000 0000000000000000000000000000
00035 00036 00037 00040 00041 00043 00045 00045 00065 00055 00055 00055 00055 00055 00055 00055 00055 00055



							Z			
	0	0	0	pos pos	37777777777777	0	0	0	LASTCELL	2
	DCT	OCT	DCT	855 855	100	DCT	DCT	OCT	EQU	EQU
	RPROG	RDMPFLG	MARKTIME	LASTOT	TOTIME	RHT	REMTIME	LASTCELL	DATE*	EXECUTE
00000	00000	00000	00000		77777	00000	00000	00000	00075	22000
0	00	00	00		~~	00	00	00		
00	00	00	00		27	00	000	00		
	99000	29000	0000	00071	P	47 000	00075	92000		

800T



All references to channel 1/2 magnetic tape units were removed (the school has no units available) and the I/O linkage for the remote display driver was inserted, see figure 6.

These modifications to BOOT altered the location of the begining of the AET and the subroutine EXTREC uses this location as an absolute address. This required recompiling EXTREC with the correct address for the AET and then placing this on the system library tape again using the routine LIBEDIT.

B. Suppression of Accounting Medium

The original version of COOP MONITOR provided for accounting information to be output on the paper tape punch. This output was of unknown format and therefore of no use to the computing center. This did demand the paper punch be selected and prevented the use of the punch as an output device. The suppression of accounting output was accomplished by taking advantage of the READ/WRITE subroutine in MCS. All I/O requests must be thru this routine and this includes any requests for output to the accounting medium, normally the paper punch. Logical number 55 is reserved for the accounting medium and to suppress the output a test for logical 55 is made each time READ/WRITE is entered. If the entry is for any logical number except 55 the request is processed. If the request is for logical 55 a no action exit is made.

This test is made by adding the following programming to the READ/WRITE section of MCS at approximately cell 1225.

INA		-55	Test for accounting
AJP	N	*+3	Jump if not accounting
INA		2	Build exit to suppress
SAU		MRW800	accounting output
SLJ		MRW800	Jump to exit



This suppresses the accounting output but still allows the paper tape punch to be used as an output medium if desired. Unless the punch is to be used as an additional output unit is need not be selected.

C. Loader Errors to the Operator

Many of the failures of programs to run under the COOP MONITOR result from errors detected by the subroutine LOADER in MCS. These errors cause messages to be written on the standard output medium and this must be listed off-line (unless the standard output is an on-line printer) before the operator can determine the cause of the error. To allow the error message to also be output on the comment-to-operator medium, normally to the typewriter, the following programming was added to the subroutine LOADER in MCS at approximately cell 6274.

RTJ	WRITE	Errors to operator	
01	53	BCD	Unit #
03	LERR	Write/Check	FWA
00	LERR+5		LWA+1
NOP		Error return	
NOP			

Loader errors are now immediately available to the computer operator as the program is being run to assist in the correction and possible rerun if desired.

D. Linkage for Remote Display

The addition of a I/O subroutine for remote operation of a digital display unit (DD65) requires that proper entry linkages be entered into MCS. This will permit the driver to be called (if not within the MCS) and executed. These linkages are in the Available Equipment Table (AET) and the Available Equipment Driver Name Table (AEDNT). Both of these links



have been provided in the present (modified) version of the library tape. In addition, a reserve area of 1000 cells has been made available within MCS (cells 3060 to 4060) to contain the programming for the display driver.

The AET entries (in BOOT) are shown in figure 6 and the AEDNT entries are located at the end of the subroutine LOADER, at approximately cell 6460 in MCS. These entries are:

BCD	DISPLAY
SEV	3070
SLJ	HOWLER

where SEV indicates the driver is within MCS and 3070 is the entry point address of the driver

This link therefore requires the display driver to have its entry point located at cell 3070 to be executed properly. If a new entry address is desired it must be entered into the AEDNT, the AET entry need not be changed.

The final modifications made to the COOP MONITOR system were the addition of two subroutines to the library tape. These subroutines were: 1. Grafplot, to allow a graph of any two designated arrays to be drawn on an incremental plotter, see section 4.1. 2. UCSD, a new Secondary Control System written by the University of California at San Diego, which allows the use of simple control cards for running "stacked job" input for compile and execution.

3.6 Specifications for Further Modifications

The modified version of COOP MONITOR is now ready for the next step in the development of an operating remote station capability. This is the programming and insertion into MCS of a remote station display (DD65) driver, the alteration of



the system interrupt handler (SELECT, REMOVE, DETECT) to allow remote station interrupts and a subroutine to display graphical information on the remote display. The specifications for these three modifications are discussed in the following sub-sections:

A. Remote Display Driver

This subroutine would allow the display to function as the comment-to-operator medium, normally the console typewriter. One of the subroutines for this driver has been completed and is fully described in section 4.2 "line printer simulator". This subroutine will produce a line by line display on the console (DD65), that will move upward with the arrival of each new line, like a typewriter. Only the upper half of the tube face should be used for the "line printer" to allow the lower half to be used as a "status board" for computer input or output assignments and any special information for the remote station operator.

To correctly process input/output requests from COOP MONITOR (from READ/WRITE) the remote display driver must accept the standard calling sequence and correctly respond to the parameters specified. The specifications for the standard calling sequence is now given in the COOP MONITOR format:

TITLE: DISPLAY

PURPOSE: To input from or output to the remote station display (DD65) in a format compatible with the COOP MONITOR.



USAGE:	Calling Sequence;		
	ENA	Location interrupt routine	
L	RTJ	DISPLAY	
	R.M.	E.C.	
L+1	F.C.	A	
	I	В	
L+2		Alternate Return (error)	
		E	
L+3		Normal Return	

R.M.= Recording Mode, 1 if format is BCD 8 char/word
2 if format is 8 typ. char/word
3 if format is 1 typ. char/word

BCD 8 char/word; implies the internal format is BCD with blanks replacing typewriter characters for which there is no BCD equivalent.

8 typ. char/word; implies the internal format is 8 typewriter characters per word.

1 typ. char/word; implies the internal format is 1 typewriter character per word.

E.C.= Equipment Code with format CRXX
C= Channel number (7 for display)
R= 1 for input, 0 for output
X= Not interpreted

I= Interrupt Selection

1= With interrupt, use the address in the A register
0= No interrupt, ignore the address in the A register



F.C. = Function Code explained below.

A, B, E = Detailed under each function code.

Functions: In all cases if a parameter error is encountered E is set equal to 0 and control is transferred to the alternate return. Parameter errors are such things as channel not equal to 7, R not equal to 0 or 1, incorrect function codes, etc. E is always set to reflect the case in which the typewriter (simulated by the display) is left. This has no meaning for the display but the correct response if necessary for COOP MONITOR. The 2⁶ bit of E is set to 1 for upper case.

F.C.=1

Starts transmission of data to or from an area specified by the first address (A) and the last address plus 1 (B). In some cases a conversion and/or packing/unpacking operation is required by the recording mode.

For input, R.M.=1 (BCD 8/wd)

Keyboard input with no interrupt on carriage return is selected. Characters are packed eight per word until the area from A to B-1 is filled or carriage return is sensed. If carriage return is sensed fill out the last word with blanks if necessary. Interrupt on carriage return is selected and an exit made with the number of words read in the A register.

$$R.M = 2 (Typ 8/wd)$$

This mode is the same as R.M.=1, except the BCD code from the display must be converted to typewriter characters.

$$R.M.=3$$
 (Typ $1/wd$)

The characters are read, converted to typewriter code, and stored one per word in area A to B-1. Interrupt on carriage return remains selected.



For output, R.M.=1 (BCD 8/wd)

The information from A to B-1 is packed into the proper format for the display and output. If the message overflows a three line buffer (186 characters) the overflow is lost.

$$R.M.=2$$
 (Typ 8/wd)

The information from A to B-l is converted to BCD and packed into the display format and output.

$$R.M.=3$$
 (Typ $1/wd$)

Same as R.M.=2 above.

F.C.=2 Check only

Control is returned with the number of words transmitted by the last read (R=1) or write (R=0) operation. This function if needed to satisfy MCS which assumes some of the transmissions are buffered and therefore it must return to the driver a second time to determine the number of words "buffered".

F.C.=3 Read/Write with checking

Same as the operation for F.C.=1, with the number of words processed entered in the A register before returning.

F.C.=4 Sense Equipment Ready

Determine if the display is in a "ready" status, if it is not ready set E to 1 and use the alternate return. If it is ready set E to indicate the current status for the "case" and use the normal return.

The present COOP MONITOR does not use any of the provisions incorporated for F.C. greater than 4. The driver routine need only check that the function code is within the range 1 to 4. If not set E=0 (parameter error) and use the alternate return.



B. Coop Monitor Interrupt Package

Before any great amount of programming can be done to adapt COOP MONITOR for remote operation, the present interrupt package (Select, Detect, and Remove) must be modified. This subroutine can presently select and sense interrupts on channels 1 thru 6 inactive and all internal interrupts. It cannot select or sense satellite generated interrupts on channels 3/4 or 5/6 via the CDC 1607 magnetic tape units, nor can it select or sense any channel 7 interrupt.

The calling sequence for the interrupt subroutine, see ref. 10, uses the integers 1 thru 12 to set the type of interrupt to be selected and sensed. The integers 1 thru 8 are used for those interrupts to be removed. These calling parameters need to be increased to provide the following additional options.

For Select:

Type Interrupt	Action			
13	Select program control for channel 3/4			
14	Select program control for channel 5/6			
15	Interrupt on keyboard 1 hit (DD65)			
16	Interrupt on keyboard 2 hit (DD65)			
17	Interrupt on radar target hit (DD65)			

For Remove:

To avoid confusion use the same parameters to remove the above selections

Before any of these changes are attempted the precautions necessary for programming an interrupt package, discussed in ref. 13, must be carefully considered.

Along with these modifications to the interrupt subroutine, the main frame of the computer should be modified to allow



computer selection of interrupt lockout. This would avoid the present procedure of selecting interrupt on arithmetic fault and then forcing a fault just to place the computer in lockout mode. There is just such a routine in MCS (RLOKOUT) to perform this function. This takes 20 instructions to accomplish what could be done with one. These modifications would be similar to those described in section 4.4 to provide computer selection of remote indicator lights.

C. Data Display Graph Plot Routine

The incremental graph plotting system has been operational for approximately six months, see section 4.1. A routine to provide this graph plot capability utilizing the Data Display unit (DD65), still needs to be completed. The following specifications and suggestions should provide an outline for incorporating this "Graph Display".

- 1. Use the author's scaling routine to scale to units per inch.
- 2. Use this scale and 16 increments per inch vice the 100 per inch used in the incremental system to build a scaled integer array of coordinate points.
- 3. Output the axis, titling, and labeling data using the standard "Grafplot" technique.
- 4. Curve drawing requires extensive use of the string capability of the display in order to provide for multiple curve graphs. This is due to the relatively small, 1024 cell 24 bit, memory of the data display.
- 5. Memory allocation in the DD65 Display should be about as follows:
 - a. Vertical and Horizontal Axis, 8 inches long. Use vector size 64/line. Requires 40 cells.



- b. Labels, 4 DD65 words/label. 18 labels requires72 cells.
- c. Titles, A minimum of about 200 cells
- d. Curves, Total memory usage of above is 312 cells. This leaves 714 cells for curves. Using the string vector mode this will provide storage for approximately 2500 vectors.
- 6. Using only the smallest vectors this will provide for approximately 20 traverses of the display tube. Assuming that an average curve traverses the tube 4 times, it appears that 5 curves may be displayed simultaneously.

Besides an on-line graph display routine, another routine which is very desirable would provide an off-line display of the graphs which were output by the CDC 1604 program for "hard copy" incremental plotting.



4.0 SYSTEM ROUTINES

Several system routines were written for both the Fortran 60 System and the Coop Monitor System. Four of these routines, which were developed, shall now be discussed.

4.1 Grafplot Routines

The 1604 Grafplot Routine, see enclouse 3, was written for the CDC 1604 computer. It generates a magnetic tape output in the format required to drive the 160A Grafplot Routine, see enclosure 2. A version of the 160A routine was written for the 160 computer, see enclosure 1. It bypasses the interpolation option in order to operate in the smaller memory of the 160 computer.

This system will produce multiple curved graphs, each curve is limited to a maximum of 900 points. Optional auto-scaling of data points, titling and curve labeling is available. Figure 7 is a general flow diagram of the 1604 Grafplot routine. Copies of the coding for these routines are available from the CDC DATA CENTER, PALO ALTO, CALIFORNIA or from the U.S.N. Postgraduate School Computing Center.

Two original techniques where developed which are of interest. They are the quantized scaling iterative procedure used in the 1604 program and the "decision rule" algorithm for providing "best fit" motion commands to an incremental plotter.

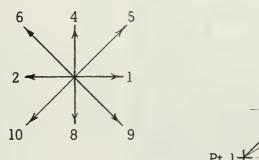
The scaling technique assumes a scale, tests for fit, then iterates to the next quantized scale and test again until the optimum available scale is found.

The two point connector algorithm, "LINE", computes the code string required to move the pen of a digital incremental X,Y plotter from an initial point (X1, Y1) to a terminal point (X2, Y2) by the "best fit" approximation to the straight line between the



points. The permitted elemental pen movement is to an adjacent point in a plane Cartesian point lattice, diagonal moves are permitted. The approximation is "best fit" in the sense that the deviation of the generated line from the true straight line never exceeds one half an increment. This is physically the best fit possible within the movement constraints imposed.

As an example of the LINE program, assume it is required to increment a pen's position with minimum deviation, along a straight line connecting point 1 and point 2. The movement codes for the CalComp Plotter are as follows;





Executing the LINE program, the following values are found;

A = 5

B = 3

NRLONG = 5

NRSHORT = 3

MOSTLY = 1

IBOTH = 5

and the iteration scheme produces the incremental path shown.

Note, in the following fortran program, LINE, a subroutine is required to output the movement codes from the user's particular computer to the incremental plotter. Thus subroutine "PLOT (MOVE)" would output the movement code "MOVE" to the plotter. For the CalComp Plotter the NCODE instructions may be deleted, since the routine is written to require no code conversion for this equipment.



```
PROGRAM LINE (X1, Y1, X2, Y2)
     DIMENSION NCODE (10)
     NCODE (1) = "user's +X movement code"
     NCODE(2) = "
                       -X
                                11
     NCODE(4) =
                     11
                         +Y
     NCODE(5) =
                     11
                        +X+Y
     NCODE(6) =
                         -X+Y
                    - 11
                                11
     NCODE(8) =
                        -Y
     NCODE (9) = "+X-Y
                                11
     NCODE (10) = "
                       -X-Y
     A = X2 - X1
     B = Y2 - Y1
     IF (A) 200,100,100
    ICODE = 1
100
     Go To 300
200 A = -A
     ICODE = 2
300 IF (B) 500,400,400
400 \text{ ICODE} = 4
     Go To 600
500 B = - B
     ICODE = 8
600 IF (A + B) 1500,1500,700
700 IF (A - B) 800, 900,900
800 MOSTLY = JCODE
     NRLONG = B
     NRSHORT = A
     Go To 1000
900 MOSTLY = ICODE
     NRLONG = A
     NRSHORT = B
1000 IBOTH = ICODE + JCODE
     LIMIT = NRLONG
     NSWITCH = NRSHORT
     MOSTLY = NCODE (MOSTLY)
     IBOTH = NCODE (IBOTH)
1100 IF (NRLONG - NSWITCH - NSWITCH) 1200,1400,1400
1200 \text{ MOVE} = \text{IBOTH}
     NSWITCH = NSWITCH - NRLONG + NRSHORT
1300 CALL PLOT ( MOVE )
     LIMIT = LIMIT - 1
     IF (LIMIT) 1500, 1500, 1100
1400 MOVE = MOSTLY
     NSWITCH = NSWITCH + NRSHORT
     Go To 1300
1500 END
     END
```



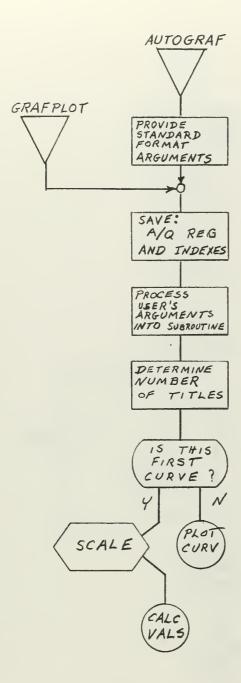


Figure 7a



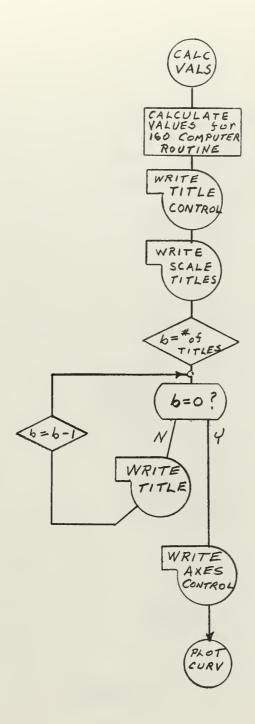


Figure 7b



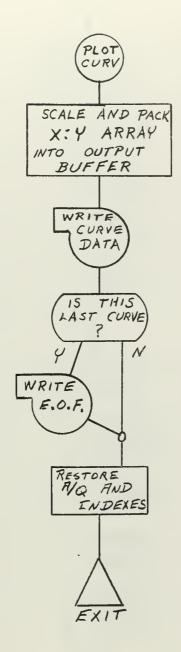


Figure 7c



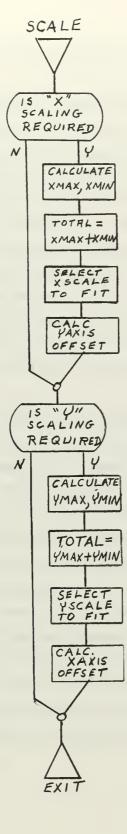


Figure 7d



4.2 Data Display "Line Printer Simulator"

The "line printer simulator" program demonstrates a very effective method of providing a continuous page listing ability. The problem was to display one full page of data on the Data Display Incorporated, Model 65, console. The data displayed was to be updated one line at a time by over-writing an old line of data in the DD65's memory. It was desired that this new line entry always occur at the bottom of the page and all other lines would precess up the page and finally disappear. An effective method to provide this listing ability was programmed and added to the Fortran 60 System. An understanding of this program requires a familiarity with the word format used to update the DD65. The DD65 has the following characteristics;

a. It has two keyboards which can be used only as output mediums to a computer. There is no connection or internal logic for providing tube display of a character when it's corresponding key is hit. This is different from a conventional typewriter, which prints it's character automatically when a key is hit. In order to display the character, it must be read by a computer, processed and the appropriate word format must be transmitted back to the display. The display logic then decodes the format of the words transmitted to its memory and displays the appropriate character/characters. There is no provision for read out from the DD65 memory by a computer. The memory serves only to store the data for display upon the cathode ray tubes. The logic cabinet of the display unit contains the circuitry required to scan its memory and display the contents onto the cathode ray tubes.



- b. To read from a display keyboard, requires that a sequence of external function codes (see fig. # 9) must be executed to sense keyboard hit, select keyboard for input to the computer, then input one word via channel 7. The BCD code for the key read-in will be the lowest 6 bits for keyboard 1 characters and the lowest 9 bits if keyboard 2 was read. The process of reading the key into the computer releases the key at the DD65 console.
- c. Output to the display maybe either characters or vectors. There are three sizes of characters, 32, 64, or 128 per line. There are two sizes of vectors, 64 or 128 per line. The line mentioned is the width of the tube display area, approximately 8.5 inches square.
- d. A selection of either character or vector mode, a memory storage address, the X / Y display position, and a tube selection are all data which is conveyed to the display. The word which contains this information is called a designator word, see figure # 8. This designator word can also carry two characters or vectors, depending on the mode selected. Additional characters or vectors can be transmitted after the designator word, if packed in a format called "string word format", see figure # 8. These "string" word characters or vectors will be positioned relative to their preceding designator word. Thus it is the designator word that controls the tube location where the character/vector string will appear. For additional display information, see reference #19.



The line printer routine provides for displaying 32 lines of data. This requires that 32 designator words, each followed by a line of data, be stored in the DD65 memory. Once the data was in the DD65 memory, it was only necessary to selectively transmit new designator words with the appropriate new Y position indicators to move the whole line's position. Thus once the line data has been output, the 1604 is not required to retain an image of the page data in its memory, nor need any time be wasted in re-transmitting redundant information to the display.

The technique employed required that a 32 word designator table be constructed. This table provided memory addresses for data storage from cells 600 thru cell 1777 in the DD65 memory. Note, the DD65 memory cells are only 24 bits long, the disassembly from the 1604 computer's 48 bit word format is automatic in the DD65 logic. Note also that equipment limitations disallow addressing odd numbered memory locations in the DD65. The designator table also provides 32 discrete, equally spaced vertical "Y" axis locations to provide seperation between the lines to be displayed.

The method of up-dating the page displayed requires that all the "Y" locators in the designator words be incremented vertically one line space (20 units). A mask search is then executed to locate the designator word which contains the "Y" locator for the bottom line entry to the page. This "Y" locator is 400. Once found, the designator word is stored in the output buffer. Then the designator table is transmitted to the DD65, thus sweeping all lines vertically one space. The new line is packed into the output buffer. This buffer now contains a



designator word followed by a line of string words. These are now output via channel 7 to the display's memory. Note the channel 7 input / output instructions transmit words, from the 1604 memory in reverse sequence compared to the normal buffer channels. This requires an inverse packing order when packing the buffer for output on channel 7.

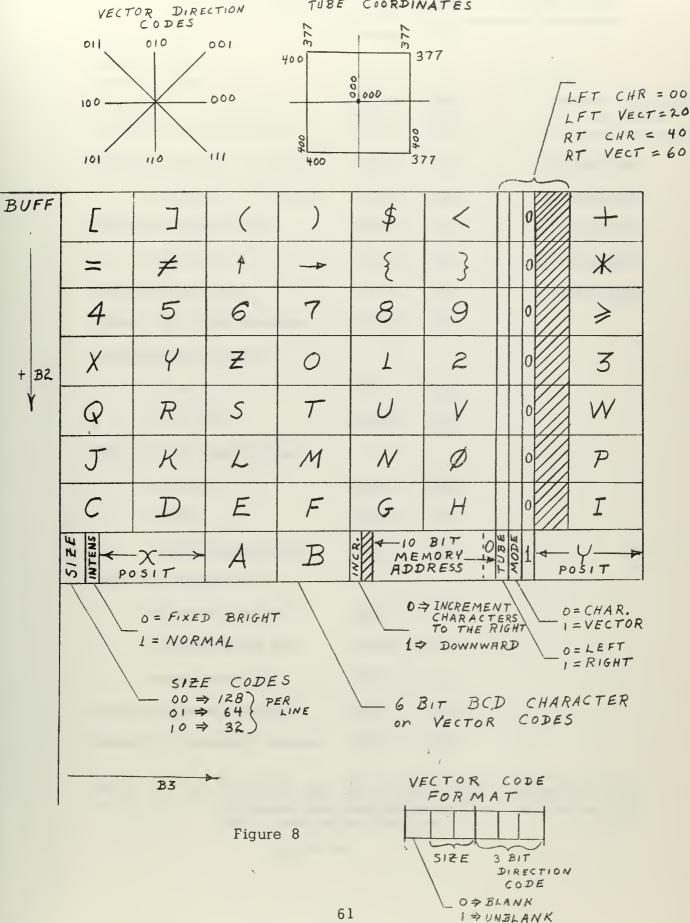
This line printer technique has also been incorporated into a typewriter page simulator for the right tube of the display.

Both systems are working well.

See appendix IV for the resident coding required for the line printer package. It required only 77 cells including the designator table and a 10 cell output buffer. The designator table is listed in the appendix IV, page # 6.



CHANNEL 7 OUTPUT FORMAT for DD65 DATA DISPLAY TUBE COORDINATES





DATA DISPLAY CONSOLE MODEL 65 ''EXTERNAL FUNCTION CODES'' 10 December 1962

SELECT	CODES				
FUNCT		Select 1604	Code 160	Computer Input Word Bit Format	
Select	: Keyboard 1 for Input	¹C7140	7140	00000FFFFF	
	Keyboard 2 for Input	C7120	7120	OOOVVVFFFFFF	
Select	Track Ball ''X''	C7102	7102	000000000000000000000000000000000000000	
	Track Ball ''Y''	C7104	7104	000YYYYYYYYY	
Select	Range Switch	C7110	7110	00000000RRR	
Select	: 160 Status Response	²(C7040)	7040		
Select Memory Update;					
	from 1604	C701 0	(7010)		
	from 160	(C7020)	7020		
Select Radar Target Data;					
	to 1604	C7002	(7002)		
	to 160	(C7004)	7004		
	to Auxiliary Equip.	C7001	7001		
Select	: Interrupt on;				
	Keyboard 1 Key Hit	C7105	(7105)		
	Keyboard 2 Key Hit	C7103	(7103)		
	Radar Pulse Hit	C7141	(7141)		
Release Interrupt Request		C7111	(7111)		
Remove All Interrupt Selects		C7121	(7121)		

Notes 1. ''C'' Indicates 1604 data channel number. (Normally, C=7)
===== 2. () Indicates code disabled selectively on ''160 or 1604
ONLY'' mode switch position.

Figure 9a



SENSE CODES

CONDITION Keyboard 1 Hit Keyboard 2 Hit Keyboard 1 NOT Hit Keyboard 2 NOT Hit	1604 Full Exit Sense Code C7172 C7175 C7174	160 Status Response *****2 ******************************
Tab Hit		xxlx
Tab NOT Hit	C7157	
Carriage Return Hit		нжж
Carriage Return NOT Hit	c7166	
Keyboard 1 Selected		жұұж
Keyboard 2 Selected		4xxx
Keyboard 1 NOT Selected	c7167	
Keyboard 2 NOT Selected	C7037	
NOT DD-65 Interrupt	c7156	
DD-65 from 160 Selected	c 7020	23000
DD-65 from 1604 Selected	C7010	lxxx
Radar to 160 Selected	C7004	ж4жж
Radar to 1604 Selected	C7002	XXXX
Radar to Auxiliary Equipment		
NOT Selected	C7001	xlxx
Radar Target Present	c7136	ж2ж
Radar Target NOT Present	C7137	
		0000

Figure 9b



4.3 Merg Sort

The SORT Routine, see appendix III, was written to improve the effeciency and reliability of sorting using the 1604 computer vice the IBM mechanical card sorter. Another motivation was to provide the capability of sorting 120 character records which could not be easily sorted using 80 character cards.

The SORT Routine can sort on variable length column fields from 1 to 120 columns. The present routine divides the field to be sorted into 7 character fields, then multiple entries are made to a subroutine, SORT7, which actually performs the sorting operation. SORT7 divides the computer's memory into three equal bins, ABIN, BBIN, and CBIN. These are each 20,000 octal cells long. SORT7 requires an input tape written in 120 character records with an "End of File Mark" terminating the file to be sorted. Upon entry to SORT7, one of its subroutines, Alsing, reads 1000 octal cards into ABIN. As each card is read, a sorting key is formed from the column field designated and this key is stored in the cell preceding the input record image from which it was generated. The key occupies one cell, the record image occupies 17 octal cells, thus each input record requires 20 octal memory cells. Multiply 20 octal by 1000 octal to obtain the arbitrary 20,000 octal bin size which was choosen as the basic block size. Alsinp always checks for an E.O.F. mark and sets a flag to signal the rest of the routine that the last block has been read. After Alsinp has read 1000 octal records or encountered an E.O.F. mark, then an entry is made to a subroutine, Rihmerg, which performs an internal merg sort by oscillating between ABIN and BBIN, sorting on the keys. The internal merg sort terminates with the sorted block in CBIN. If this was the first block, it is immediately written onto one of the two scratch tapes and Alsinp inputs another block. If this was not the first block, then a subroutine, Hexsort, is entered to perform a merg of the new block



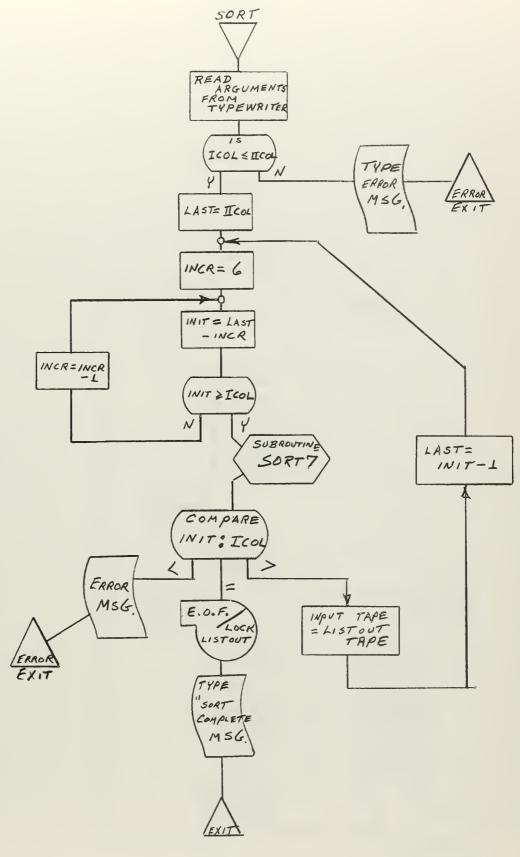
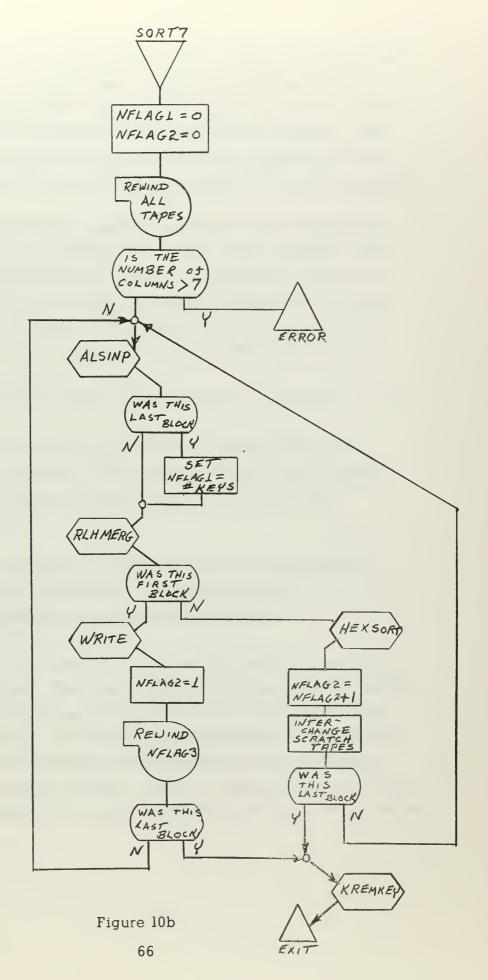


Figure 10a







into the file of previously sorted blocks which are accumulated externally on a scratch tape. This cycle continues until an E.O.F. is encountered, then after the external merg is complete, the scratch tape is rewound and a subroutine, Kremkey, reads in the ordered blocks from the scratch tape, removes the keys and writes out the output file in an ordered, 120 character record length file.

If additional fields remain to be sorted, this output file is designated the input and another entry is made to SORT7 with the new character field's initial and last column numbers as arguments. This procedure continues until the total sort field is in order and listed on the output. The output is then rewound to lockout and the operator is informed that the job is finished.

Several improvements to this routine are suggested.

- a. Build and sort on a two cell key, if large fields are to be sorted frequently. This would provide a better balance between the internal sorting time and the external tape handling time.
- b. Provide for sorting on split fields, ie. non-consecutive
 column fields. This could be provided by forming
 the sort key piece-wise from specific columns.
- c. Use a double entry key / key location table for performing the internal sort. This would eliminate the necessity of carrying the input record image around with the key each time the key order is changed. The sort could be performed by ordering only the keys and maintaining correspondence in the key location table as the keys are sorted. This key location table could then be used to perform the internal ordering of the input record images.



This scheme would improve the internal sorting speed and reliability since it would require fewer internal data transfers.

d. The last and probably the most significant improvement which is indicated, would be to utilize two more scratch tapes. This would improve the sort routine speed by nearly 50%. This is due to the rewind time required by the tape drives and their inability to read in the reverse direction. At present, much time is wasted waiting on the two scratch tapes to rewind in order that the next internal block can be merged with the external ordered file. A suggested method to improve the external sort would be to alternate the merging of the internal block between to sets of scratch tapes similar to the set presently employed. This would increase the rewind time available for each set and thus decrease the idle time mentioned previously. After Hexsort has finished merging the last block, then Kremkey would have to operate differently than at present. Kremkey would have to read one block from the ordered tape of each scratch tape set, then perform a final merg comparison similar to the Hexsort merg routine. Instead of forming an ordered list in memory, this final merg could be written out as the final ordered, 120 character listable output. Before any other modification is considered, this last suggestion should be given priorty "one". At present it remains a gross deficiency against high speed sorting using this routine.



4.4 Satellite System Programming

There are two basic operations necessary to establish an adequate satellite system. These are the ability to exchange data and to selectively execute a pre-stored program when directed by another member of the satellite system. The present installation proposed to couple the CDC 160 to the CDC 1604 Computer. The CDC 160 Computer does not provide an interrupt mode, therefore only the 1604 interrupt mode was available to be employed.

The desirable characteristics of the basic 1604 satellite interrupt program are:

- a. Reliability
- b. Flexibility
- c. Speed
- d. Effective Employment of the Communication Flags
- e. Minimize Memory Requirements

The problems encountered in designing the basic 1604 interrupt routine shall now be discussed. The 1604 Computer is unable to prevent the 160 Computer from entering the interrupt auxiliary routine which is wired into the 1604. For this reason, a protective "lock-out" scheme was required to prevent interference with the 1604 equipment handling routines. Specifically, there exists a critical time interval between equipment selection and activation during which an interrupt from a satellite station would be disastrous to the main program. The technique develope to prevent this, is as follows: All 1604 equipment handling routines were modified to turn on communication flag I (see ref. # 2) in advance of any equipment selection. Communication flag I is then cleared after the selected equipment is activated. Using this scheme it is



then required that the 160 satellite computer irespect communication flag I prior to executing an interrupt. If flag I is set, then the 160 computer enters a "wait loop" until flag I is cleared by the 1604 Computer. Thus through the use of communication flag I, the 1604 computer is, in effect, capable of "locking out" the 160 satellite computer from an interrupt request. This was a desirable feature not presently provided in the hardware design.

The next problem in the design of the interrupt routine was how to indicate to the 1604 computer, the nature of the task requested by the 160 computer. The method used requires that each interrupt shall immediaty trigger a , 48 bit word , data transfer to the 1604. The format of this word, designated as the "control word", is outlined in detail in figure # 12. After receiving this "control word" the 1604 interprets the operation to be performed. There are four tasks which can be directed by the control word, they are:

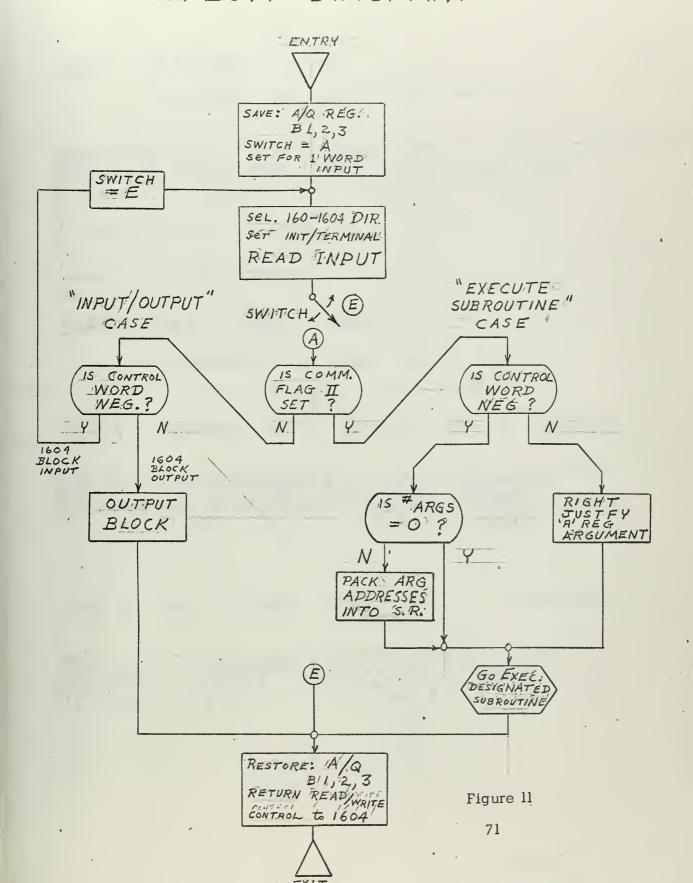
- 1. 1604 INPUT DATA BLOCK
- 2. 1604 OUTPUT DATA BLOCK
- 3. PACK ARGUMENT ADDRESSES INTO A SUBROUTINE AND THEN EXECUTE THAT SUBROUTINE.
- 4. LOAD "A" REGISTER WITH A 21 BIT ARGUMENT FROM THE CONTROL WORD AND THEN RETURN JUMP TO EXECUTE THE SUBROUTINE.

A flow diagram of this 1604 satellite interrupt routine is provided in figure # 11.

One additional problem remains to be discussed, that is storage allocation for the programming required by the satellite system. This was acquired by setting the resident bias level on the Fortran 60 System to 5000 octal, vice the normal 4000.



1604 INTERRUPT ROUTINE FLOW DIAGRAM

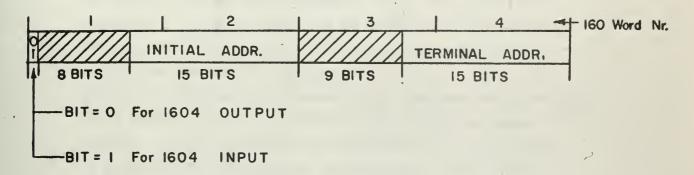




160-1604 SATELLITE CONTROL WORD FORMAT

DATA TRANSFER MODE

INTERRUPT WITH COMM FLAG II "NOT" SET



SUBROUTINE JUMP MODE

INTERRUPT WITH COMM FLAG II "SET"

TYPE I, ARGUMENT IN "A" REGISTER, RTJ TO SUBROUTINE

	q		1		_
_		21 BIT, INTEGER ARGUMENT SIGN BIT WILL BE EXTENDED		SUBROUTINE ADDRESS	
	2	21 BITS	9 BITS	15 BITS	7

TYPE II, PACK ARGUMENT ADDRESS, RTJ . To SUBROUTINE

-		1		
Nr. of ARGS	1 st ARGUMENT ADDRESS		SUBROUTINE ADDRESS	
2 6 BITS	15 BITS	9 BITS	15 BITS	\neg



This provided the memory space needed to store the satellite programming plus an additional "buffer" area for receiving transient subroutines from the 160 computer. These subroutines may the be executed by an interrupt entry to the 1604 computer via the satellite interrupt system.

The use of the 160 as a satellite station requires that the modified library tape, FORTSAT, be in use by the 1604 computer. Also, the 1604 must be operating under monitor control in order to utilize a remote monitor process routine which was developed by the authors' (see ref. # 22). The physical seperation of the satellite 160 computer station required some means of sensing the above conditions at the remote station. Visual indicators were selected as the best method of implementing the required status sensors. The console of the 160 Computer contains many unused indicator lights, two of these were selected to be used as status indicators. The first light, designated # 1 or FORTSAT, is a blue-green background field light at the left end of the "P" register. The second light, designated # 2 or MONITOR, is the next blue-green background field light to the right of the # 1 light.

Manual control of these lights at the console of the 1604, was considered an unnecessary burden to the operator. Computer selection would be more convenient and the status indications more current in the reflection of the actual status of the 1604 Computer operations.



To enable computer control of the indicator lights, two new select codes (on - off pairs) for the 1604 were required. As all satellite selects are made in the 1607 Magentic Tape Logic Cabinets, modification of these units was necessary. This modification would allow the 1607 to accept and decode the new indicator light codes. The two codes selected were;

LIGHT # 1 (FORTSAT) "ON" 53511

"OFF" 63511

LIGHT # 2 (MONITOR) "ON" 53544

"OFF" 63544

The select code format is as follows:

First digit; Channel number Second digit; Cabinet number

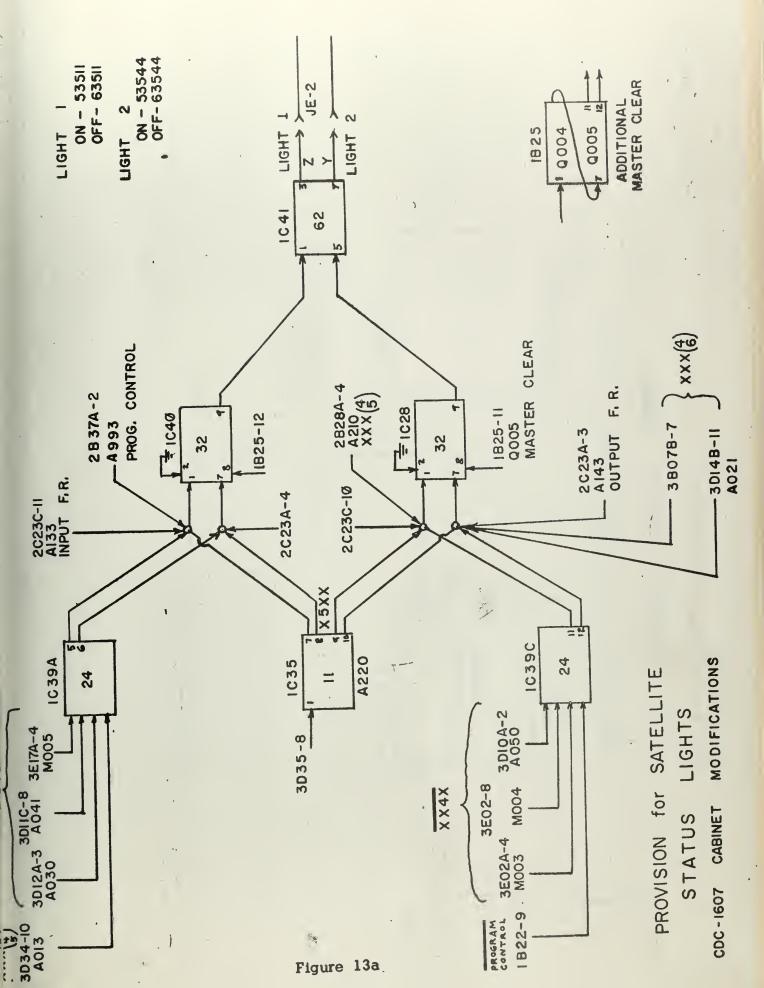
Third digit; Group code, 5 for satellite

Fourth & Fifth; Condition code

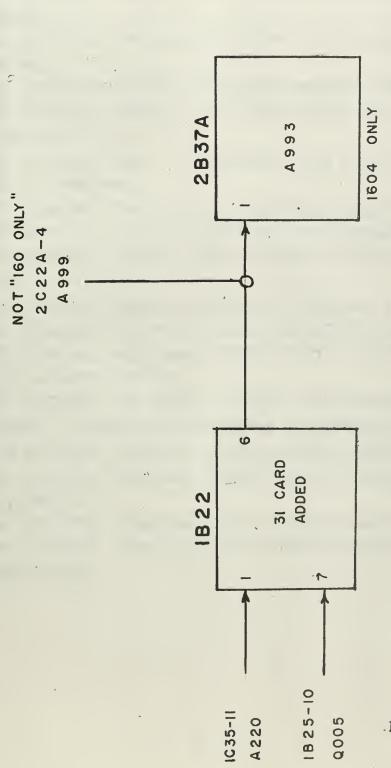
The two codes selected for the indicator lights contain the false cabinet number 3. This was necessary because the 1607 (cabinet # 2) does not uniquely decode the last two digits of any select code. Therefore, to prevent interference with any of the existing codes, a false 3 was used.

To avoid the need for manual selection of "program control" mode of operation for the 1607 Tape Cabinets, when enabling the satellite station, this selection was wired to be controlled by light # 1 and the master clear switch. Initial turn on of light # 1 selects "program control" and the Master Clear disables both lights and removes the program control selection. The logic diagrams for the modificiations made to the 1607 Tape Cabinets are shown by figure # 13. Two relays were added to the 160 to provide switching of the two lights provided.









of "PROGRAM CONTROL MODE"
CDC 1604 CABINET MODIFICATION

PROVISION for EXF CODE CONTROL

Figure 13b



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 21 DECEMBER 1962



APPENDICES



APPENDIX I

LIBEDIT PROCEDURE

There are two publications available to assist a user of COOP MONITOR in performing a successful library preparation or modification. These are ref.17 and 10. The following was obtained from these two sources together with additional remarks by the authors to aid in the understanding of the procedure.

A. Library Tape Format

The library tape is composed of two files. The first file contains three records in absolute binary format. These are:

- a. Bootstrap routine (BOOT)
- b. Recovery routine (EXTREC)
- c. Master Control routine (MCS)

The second file contains the subroutine library and starts with the "directory". This is followed by the library subroutines each consisting of one record (the system can accept subroutines with more than one record but the present library has none) composed of contiguous relocatable binary card images. Each subroutine is identified and defined in the directory by the following.

A subroutine name

Number of records in the subroutine (normally 1)

Number of common blocks assigned

Names of those common blocks

Length of each common block

Range of the subroutine (FWA and LWA+1)

Number of entry points to the subroutine

Entry point names

Number of external symbols referenced

External symbol names



The order in which the subroutines are identified in the directory must be the same as the order of appearance of the subroutines in the file. The identifying name, each entry point name, each external symbol and each common block name must have the following properties:

- a. Eight BCD characters in length, no imbedded blanks
- b. Leading character not digital or blank, except common block The first library subroutine defined in the directory is the Master Control System called "Resident". The length of Resident and all named entry points are defined. External references are not made within the resident program. There are no entries in the directory for the subroutine EXTREC.

The recommended layout of the library subroutine file is:

- 1. Directory (this <u>must</u> be first)
- 2. I/O drivers for standard medium
- 3. All other I/O drivers
- 4. Secondary Control Systems (SCS)
- 5. Any other subroutines
- 6. SNAP (selective dump routine)
- 7. MAP (produces a memory map of loaded programs)
- 8. Systems such as FORTRAN, CODAP1, ALGOL, etc.
 This layout facilitates one pass loading of library subroutines.
 The sequence for loading library subroutines will be:
- 1. I/O drivers for the standard mediums.
- 2. I/O drivers for the current job.
- 3. The desired secondary control system.

B. Directory Format

The directory is a set of 8 different types of cards for each subroutine in file 2 of the library tape. These must be ordered in the directory deck in the same sequence as the routines appear



- in file 2. Care must be exercised to assure the directory reflects the exact composition of the subroutine file, otherwise errors will result. Each set of directory cards must contain:
- 1. A card with the subroutine name, left-justified, in columns 1-8.
- 2. A card with a 16 digit <u>octal</u> integer, left-justified, in columns 1-16. This has the format:

000KKKKK000RRRRR

where 000 is zero

KKKKK is the number of common blocks required by the subroutine

RRRRR is the number of records the subroutine occupies on the library tape (usually 1)

- 3. If KKKKK is not zero, there must be a number of cards equal to KKKKK containing the name of each common block. The name is punched, left-justified, in columns 1-8. The card may be blank if no name for the common block is given.
- 4. If KKKKK is not zero, there must be a number of cards required to define the lengths of the common blocks. These cards contain <u>octal</u> integers separated by commas. The integers specify the length of the common blocks named by the cards in #3 and the lengths must be in the same sequence as the names. Any number of integers, more than zero may appear on a single card. The last integer on the card must be followed by a blank. The number of cards required depends on the number of common blocks and the packing of lengths.
- 5. A card with a 16 digit <u>octal</u> integer, left-justified, in columns 1-16. This has the format:

PPPFFFFFXXXLLLLL

where PPP is the number of entry points to the subroutine (must not be zero)

FFFFF is the relative first word address of the subroutine (FWA)



is the number of external symbols referenced
by the subroutine

LLLLL is the relative last word address plus 1 of the subroutine (LWA+1)

- 6. The number of cards equal to PPP, each containing an entry point name, left-justified, in columns 1-8. There must be at least one such name.
- 7. The number of cards required to define the entry point addresses. These cards contain <u>octal</u> integers of 1 to 5 digits separated by commas. The integers specify the relative address of the entry points named on the cards in 6. The entry point addresses must be in the same sequence as their corresponding entry point names.
- 8. The number of cards equal to XXX in 5. If this is greater than zero, each card just contains the external symbol name, left-justified, in columns 1-8. These external symbol names must be in the same order as they were defined during the assembly or compilation of the subroutine.

The sets of directory cards are preceded by a card with "DIRECTRY" punched in columns 1-8 and followed by a card with "77777777777777" punched in columns 1-16.

C. Edit Input

The input data for editing a library tape is composed of control cards, directory cards, and program information. The program information is in the form of relocatable binary cards and this binary format must be thoroughly understood by the user to perform a successful LIBEDIT. Appendix III of ref.10 gives a complete description of this binary card format.

The input data must be on the standard input unit along with the required MCS control information ("begin job" and "mcs" cards). The next card of the edit input deck must



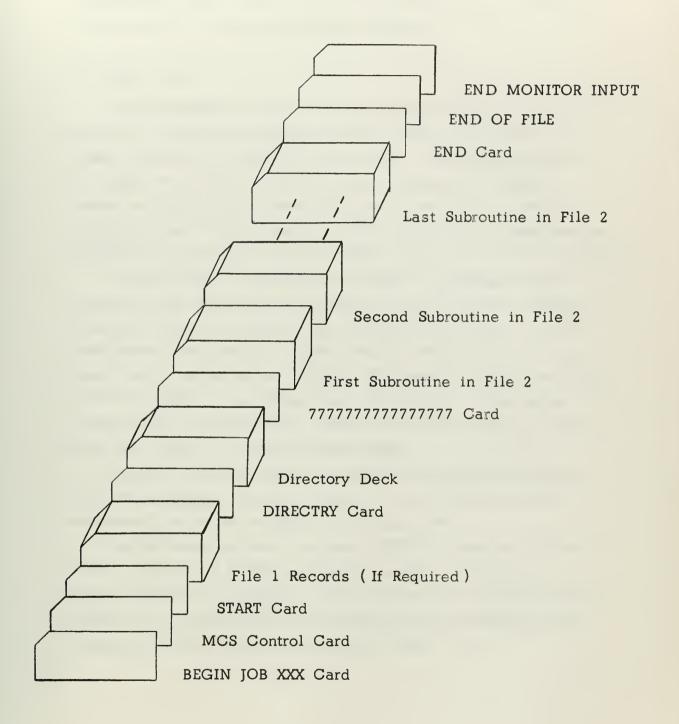


Figure A.2 Edit Input Deck



be a START card. This card contains the word "START" in columns 10-14 to produce a library tape of the same format as the old, see ref.17 for other formats possible. The succeeding cards in the input deck are determined by the type of edit and the file of the library affected.

D. File 1 Edit

The information in file 1 is in <u>absolute</u> binary format, and the file is divided into three records. Each record must be added, replaced or deleted as an entity. The information to be added or replaced must have been prepared by CODAP1 using the ORG pseudo instruction and it must be a complete, <u>absolute</u> binary format program. The complete deck produced by CODAP1 is included (only the "begin job" card need be removed).

The edit input is composed of decks of <u>absolute</u> binary records, each preceded by a control card. This card contains a decimal integer in column 10, followed by a blank, R, or D. The integer specifies the record position within file 1 of the binary card images which follow. The blank specifies the record is to be added, R to replace, and D to delete. The decks composing the records must appear in the same order in which they will appear on the new library tape.

If any of the entry points in MCS are altered by this edit then the <u>complete</u> directory (with the new MCS entry point addresses) must be included in the edit input.

The Extended Recovery routine (EXTREC) uses the AET and flags contained in BOOT as absolute address locations. If these locations are changed, then they must be changed within EXTREC (by recompiling) and including the new EXTREC deck, between BOOT and MCS, in the file 1 edit.



E. File 2 Edit

The information in file 2 is in several records in relocatable binary format. The first record is the directory. A new version of the directory need <u>not</u> be included in the edit input deck when the changes to file 2 are replacements which do not affect record lengths or entry points. In all other cases the complete directory must be included.

The first record of each subroutine (normally there is only one record) must be composed of relocatable binary card images produced by CODAP1. For edits involving subroutines of more than one record see ref.17. Each record must be preceded by a control card containing the subroutine name, left-justified, in columns 1-8, a blank in column 9, and a decimal integer starting in column 10 followed by a blank, R, or D. This integer specifies the position of this record within the records of this subroutine (usually 1). The blank specifies that the record is to be added; R specifies it is to replace an existing one, D specifies it is to be deleted. If a D appears, a binary deck for that record must not appear in the edit deck.

The edit deck, see figure A.2, must be terminated by a card with the word END in columns 10--12. To finish the input job an "END OF FILE" and a "END MONITOR INPUT" are necessary.

F. Operation

The library edit program is called from the library as the Secondary Control System by a MCS control card. The edit input is read from the standard input unit; a new library tape is written on the logical unit #13; operating information is



written on the standard output unit and the comment to operator unit.

For an edit operation the MCS control record (card) might appear: ${}^{7}_{9}ELT, MGH, 34000, O/13, 5, 1000$.

During operation of the program, a listing is produced on the standard output unit. This listing contains each control card as it appears in the edit deck, all directory cards, and a message PREV REC X for each record transferred from the existing library to the new tape. The completion of the operation is indicated by the message EDIT COMPLETED. A sample edit listing is shown is figure A.l. Error diagnostics are written on the standard output unit and the comment to operator medium as errors are detected. These diagnostics are explained in table 1.



```
START MONITOR RUN.
BEGIN IOB 234
ELT, 222, MGH, O/13, 5, 1000.
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PREV.
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      RESIDENT
      0000000000000000
      0430007700014557
      READ*
      WRITE*
      SELECT*
      1205
      1212
      655
      TYPEI/O
      0000000000000000
      0010000000300277
      TYPEI/O
      0
      CBF1*
      CBF2*
      SELECT*
      CARDREAD
      0000000000000001
      0010000000200466
      WRITE*
      LOADER*
      7777777777777777
PREV.
      TYPEI/O
                1
      CARDREAD 1R
PREV. PTI
                 1
                 1
PREV. PTLOG
PREV. BFT
                 1
PREV. MAP
PREV. LIBEDIT
                 1
PREV. COPY*
                 1
                                 Figure A.1
EDIT COMPLETED
                                 Sample Edit Listing
```



TABLE 1 LIBRARY EDIT ERROR DIAGNOSTICS

CKSUM ERROR XXXXXXXX LTN-50

An input column binary card checksum detected to be in error. XXXXXXXX will be the record number if the error is detected during a file 1 edit; or it will be the name of the subroutine if the error is detected during a file 2 edit.

DIRECTRY ERROR

An error has occurred in the directory.

DIROFLO ERROR XXXXXXXX

One of the eight directory tables requires more than 1/8 of available core. XXXXXXXX will be the name of the routine.

EDITINP ERROR XXXXXXXX

The order of the attempted edit is incorrect or incompatible with the directory. XXXXXXXX will be the name of the routine.

END OF TAPE

An end of tape mark is encountered during writing of the new library tape.

EPT ERROR

Two routines in the directory have the same entry point names.

OFLCORE ERROR XXXXXXXX

Available core is not large enough to allow forming a record. XXXXXXXX will be the record number if the error occurs during a file 1 edit; or it will be the name of the routine if the error occurs during a file 2 edit.

RANGE ERROR XXXXXXXX

An inconsistency exists between the IDC and RBD cards of a file 2 binary deck. XXXXXXXX will be the name of the routine.



READING ERROR XXXXXXXX LTN-YY

- A. A persistent (not cleared after three tries) parity error or illegal BCD character is encountered when reading the library tape or the standard input unit.
- B. An illegal or impossible number is detected on an edit control card. XXXXXXXX will be the record number if the error is detected during a file 1 edit; or it will be the name of the routine if the error is detected during a file 2 edit.

YY will be the number of the logical unit number on which the error was detected. 00 for the library or 50 for the standard input unit.

WRITING ERROR XXXXXXXX LTN-13

A persistent (not cleared after three tries) parity error is encountered when writing the new library tape. XXXXXXXX will be the number of the record if the error is detected during a file 1 edit; or it will be the name of the routine if the error is detected during a file 2 edit.



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GRAFPLOT

GRAFPLOT - AUTOGRAF
FORTRAN COMPATIBLE SUBROUTINE FOR PLOTTING DATA
R.L. HOGG / D.C. GLOVER 1 APRIL 1963
J.S. NAVAL POSTGRADUATE SCHOOL
MONTEREY, CALIFORNIA

INPUT PARAMETERS FOR GRAFPLOT ENTRY

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HOSG/GLOVER 1963

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	BUILD NORMAL RETURN GO SCALE X		SET ABSOLUTE YMAX OR (=0 IF YMAX IS	ABSOLUTE YMIN OR (=0 IF YMIN IS +	SET FOR Y SCALING	BUILD NORMAL RETURN GO SCALE Y
TOTAL #+2 SCALEX	SCALEX SCALEX SCALEX X/YSCALE XSCALE ENGTH WIDTH CALCOFFS	I YOFFS SCALEX Y** NUMAPTS MAX/MIN	HPZ	AAYMIN AAYMIN AAYMIN HEIGHT		SCALEY 2 2 SCALEY SCALEX/Y X/YSCALE
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YMODES 0 AMAX AMIN TOTAL GETTOTAL	O AMIN TOTAL CETTOTAL	O MODEOCK **	= 63 F 20 INGOUT	ITEMP = 10 ERROR	SOUT	=0 X/YSCALE ERROR	ENDGOUT	ERROR	ENCODE	* *	- ω +		ok (1) ×	ALLZEROS	* *
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CHECK TAPE WRITE



CAL IFUNIT TO CHECK WRITE ZRO. O.K., OUT BIT 47 NEG.=EOT TRY TO REWRITE 3 TIMES	IF NOT CORRECTED, THEN IGNORE IT REWRITE, TRY 3 TIMES		EOT LAST RECORD OK GET NEW TAPE OUT	EOT WITH BAD PARITY	GET NEW TAPE REWRITE LAST RECORD	EXIT RESET COUNTER TO TRY 3
1 TPCHK 1 0 TPPAR2 48 IFUNIT IFMSK 3 TPE 3 TPEOT 0 TPE	= 48 BKSP ERROR* = 1 BUFOUT	# * * * * * * * * * * * * * * * * * * *	1 TPEOTP = 48 NEWTAPE TPE	= 48 BKSP ERROR*	= 48 NEWTAPE TPPAR1	1 **
AND POPUL AND POPUL POPU	RHE RAN HNN HIN LOA CLA	ZRO ZRO RTJ SLJ	SET	RTJ	ENA SLJ	O CT OCT OCT
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CALLED WHEN EDT FOUND WRITES DOUBLE END OF WRITE TWO EDFS	REWIND WITH LOCKOUT	TYPE MESAGE	8, MOUNT NEW TAPE AND START -R-	
1 ** ** ** ** ** ** ** ** ** ** ** ** **	W R I T E *	WRITE* 54 MESAGE MESAGE+5 ERROR*	NEWTAPE TAPE 4	2 - 2
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						XMODE5 =80	2252 PLOTEST	66374 FLOATF 66114 BUFINOUT	00655 SELECT* 01760 GETCH* 02045 RELOCOM* 02613 EXIT* 007246 RECLIM* 01737 CBF* 01746 CBF** 01746 CBF** 01745 CBF** 01746 CBF*
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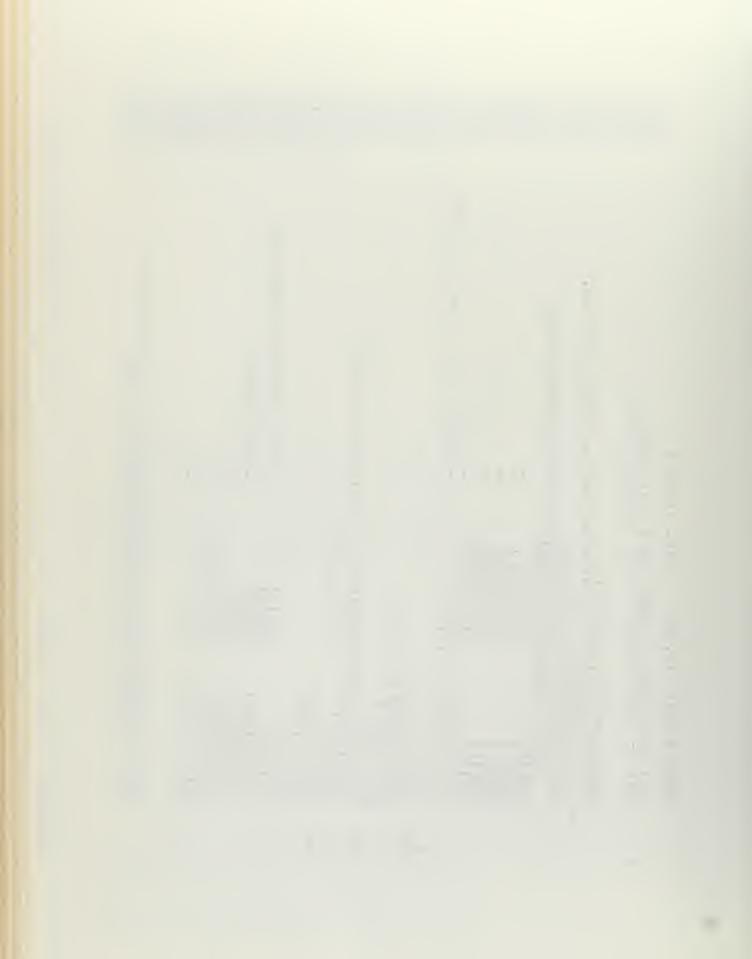
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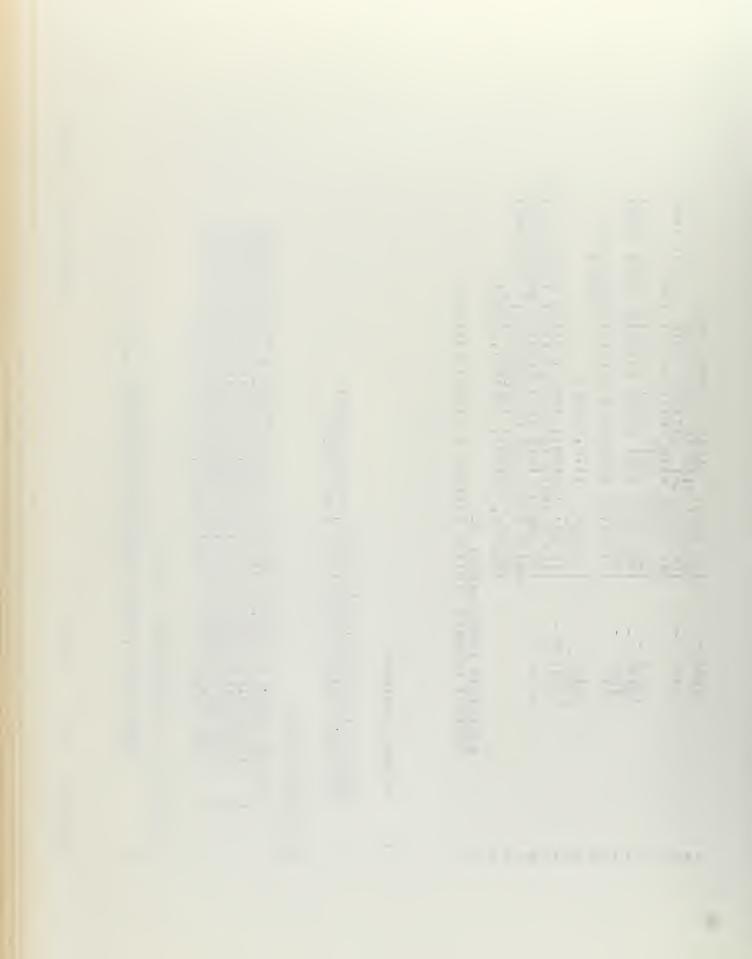
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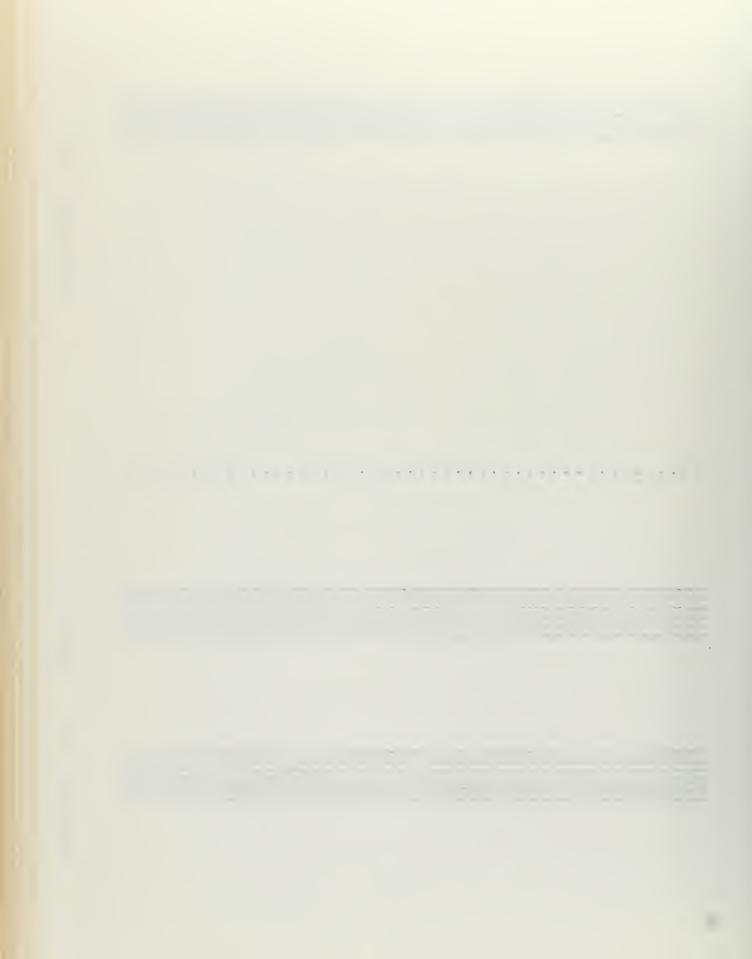
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INA(3200B) ALS(3174B) SAUS(34) SAUS(35) LDAI(R+9) LDAI(R+9) STQII(R+10) EXFS(N) + 39) STAI(R+2) STAI(R+1) STAI(R+10)	WRITE SWITCH SSK(3M) SSK(2M) EQSK(2M) LDQ(663) INA(-128) ENA(638) SLJ(4AEX) EQS(2M) THS(9) EQS(638)
3 A E X	* BCD



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SENSE PUNCH-CARD MEDIUM SENSE ON-LINE PUNCHING SENSE ALL CHANNELS INACTIVE GO FORM CARD IMAGE SENSE CHANNEL INACTIVE TRANSFER TO BUFFER SENSE LISTABLE-OUTPUT TAPE SENSE LISTABLE-OUTPUT TAPE SENSE LISTABLE-OUTPUT TAPE SENSE CHANNELS INACTIVE TRANSFER TO BUFFER WRITE NEXT BLOCK FROM BUFFER WRITE NEXT BLOCK FROM BUFFER	SENSE NO MONITOR CONTROL GO READ BINARY RECORD EXIT THROUGH 13	SENSE NO MONITOR CONTROL GO WRITE BINARY RECORD
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AJP (L+12) SLJ4 (86) SLJ4 (86) ZRD(0) ZRD(0) ZRD(0) SLJ4 (17 L40) SLJ4 (17	SLJ4(12A) ZRO(0) ZRO(0)	SLJ4(3G) ZRO(0)
LDA(6M) SCLJ4(5M) SCLJ4(5M) SCLJ4(5M) SCLJ4(5M) ENDA(6M) ENDA(6M) ENDA(6M) ENDA(6M) ENDA(6M) ENDA(6M) INA(6174B) SAULITHON ENTROM SSSK(1147) SSSK(1	READ SWITCH SSK(2M) SLJ4(1I) SLJ(2+138)	WRITE SWITCH SSK(2M) SLJ4(10)
t A E X	* BIN	* BIN 6A

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01065	01066 01067 01070	01071 01072 01073	01074 01075 01076	00100000000000000000000000000000000000	001105	011113 011114 01115
EXIT THROUGH 14	SENSE NO MONITOR CONTROL BACKSPACE EXIT THROUGH 15	SENSE NO MONITOR CONTROL REWIND EXIT THROUGH 16	SENSE NO MONITOR CONTROL ENDFILE EXIT THROUGH 17	SET TO PICK ARGUMENTS TRANSFER ARGUMENTS CALL NEXT LINK GO EXECUTE ASSEMBLED PROGRAP	SENSE NO MONITOR CONTROL GO OUTPUT BCD MESSAGE EXIT THROUGH 25 SENSE FORTRAN-E EXIT TO STACK MESSAGE	SENSE LIBRARY TAPE
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ZRO(0)	SLJ4(12A) SLJ4(7V) ZRO(0)	SLJ#(BG) SLJ#(1V) ZRO(0)	SLJ4(12A) SLJ4(5V) ZRO(0)	INA(1) LDA7(N) LDA7(N) SLJ4(1C) ZRO(0)	SLJ(L+3) ZRO(0) ZRO(0) SAL(L+2) SCM(R3) ENA(N)	ENIT(3) SLJ(L+2) ZRO(0)
SLJ(Z+14B)	BACKSPACE SWITCH SSK(2M) SAL(8V) SLJ(Z+15B)	REWIND SWITCH SSK(2M) SAL(2V) SLJ(Z+16B)	ENDFILE SWITCH SSK (2M) SAL (6V) SLJ (2+17B)	CHAIN CONNECTOR A SAL(L+1) STA(3C) STA(2C) STA(2C) SLJ(1Q)	A SSK (2M) SLJ4 (6G) SLJ4 (6G) SLJ (2+25B) SAU (1+1) LDA (N) AJP (2+25B) SLJ (2E)	TAPE ASSIGNMENT CHE A SLJ(N) EQS(1) SLJ(12A)

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EXIT/ENTRY LIBRARY MEDIUM REMIND LIBRARY MEDIUM CLEAR TRANSIENT PROGRAMS RESET PROGRAM BIAS POSITION NAMES LOOP READ BINARY BLOCK READ BINARY BLOCK READ BINARY BLOCK SENSE NO PROGRAM-NAME STORE PROGRAM NAME PROCESS PARAMETERS SENSE OVERFLOW OF MEMORY	HO3 G/GLOVER
SLJ(L+ 10) ZRD(0) ZRD(0	PAGE 21
SLJ(N) ZRD(O) ZRD(C) ZRD(C)	ENDIX - IV -

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COPY WORD SENSE UPPER RELATIVE ADDRESS MODIFY UPPER ADDRESS SENSE LOWER RELATIVE ADDRESS ADVANCE PROGRAM ADDRESS LOOP READ BINARY BLOCK SENSE END OF PROGRAM ADVANCE BIAS SENSE COMPLETION OF CALL	. REWIND LIBRARY MEDIUM	XI T EWIND	• ERROR EXIT	EWIND LI	RESET 160 LIB CALL LOCK-OUT		EXIT/ENTRY EXIT	
STA1(3C) STA7(143) SLJ(L+3) SLJ(L+3) SLJ(L+2) SLJ(C+3)	LJ(L-1 LJ4(9C) RD(0)	R	LU (25) UNI (25) UNI (27) TA (77) TA (67)	R C C C C C C C C C C C C C C C C C C C	L J (L L (L J (L L (L L)(L L (L L)(L)(L)(L)(L)(L)(L)(L)(L)(L)(L)(L)(L)(L	CALL	ENA(J) ENI(7) ENI(7) STA(3C) STA(2+478) ZRO(0)	œ
ENADA (C+5) SSH(R+2) SSH	SK4(7 DA(2C LJ4(1	LJ(1C) DA(2C) LJ4(1V	NA (E3)	1000 1000 1000 1000 1000 1000 1000 100	XNLA XNL XA (S) (S) (S)	TIALIZE FOR NEXT	SLJ(N) STA(C+2) STA(C+4) ENA(0) IJP1(L-1) SLJ(10C)	OR MESSAGE HANDLE
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SENSE FULL MONITOR CONTROL SENSE ERROR EXIT FROM COMPILER GO OUTPUT ERROR MESSAGE EXIT TO MONITOR	EXIT/ENTRY GO SENSE CHANNELS INACTIVE STRING OUT BCD CODE OUTPUT MESSAGE EXIT	EXIT/ENTRY TABLE ITEMS TO INDEX REGISTERS EXIT	EXIT/ENTRY TABLE ITEMS TO INDEX REGISTERS EXIT
SLJ4(5G) LDQ(34) SLJ(13M) LDQ(4X) SLJ4(3E) SLJ(10M)	MESSAGE SAU(L+2) SLJ4(3G) SLJ4(3G) ENIZ(3) ENIZ(3) INIZ(1) SLJ(L+4) SLJ(L-4) SLJ(L-4) SLJ(L-4) SLJ(L-4) SLJ(L-4) SLJ(L-4) SLJ(L-4)	ER LOADER STA(T) LDQ1(50) LDQ(73) QRS(3) SAU(L+1) ENI2(W) ZRU(0)	TER LOADER STA(T) LOQ1(50) SAL(L+2) LDL(73) ENIZ(N) SLJ(L-5)
SAU(L+1) ENA(N) QJP2(ZE) AJP4(6G) EXF(1000B)	T PACKED BCD LJ(N) NA(0) NA(0) NA(0) DQ1(2) JP(L+4) NA(0) SK3(7) NI(20B) NA(20B)	INDEX REGIST [1] [1] [1] [1] [1] [1] [1] [1] [1] [1]	INDEX REGIS J(N) L(7B) S(3) S(3) U(L+1) II(N)
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. GO SENSE TYPEWRITER . RETURN VIA CELL 31	EXIT/ENTRY GET CARRIAGE RETURN SELECT CHARACTER MODE PICK NEXT WORD TABLE LOOKUP SENSE CARRIAGE DOWN SENSE CARRIAGE UP SHIFT CARRIAGE PRINT CHARACTER GO SLOW DOWN TYPEWRITER SENSE END OF WORD LOOP	SET COMM FLAG1 GO DELAY RETURN	• EXIT/ENTRY • DELAY • RE-STORE INDEX / GO EXIT	
SLJ(53) ZRD(0) ZRO(0)	SAL(L+3) SLJ4(7G) ENFT(21B) STA(T+1) ENIGO ENIGO ENIGO ENIGO AJPI(57B) AJPI(57B) AJPI(57B) AJPI(57B) STA(T)	DELAY ROUTINE EXF(625408) SLJ4(1DLAY) ZRO(0)	LO SI SL SL	OUTINE
F(625608) J4(5G) J(Z+318)	SLJ(N) ENA(RS) ENA(RS) ENA(RS) ENA(RS) ENIZ(7) LDQ(T+1) STQ(T+1) STQ(T+1) STQ(T+1) STA(T) LDQ(T7R) LDQ(T7R) LDQ(T7R) ENA(T	SLJ(N) SIJ(L+4) SLJ(L-2)	ITER SLOW-DO	EWRITER PRINT RO
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EXIT/ENTRY GO SET COMM FLAG1 SENSE CARRIAGE UP SHIFT CARRIAGE DOWN PICK NEXT WORD SENSE END OF PRINT CODE PRINT CHARACTER GO TO SLOW DOWN TYPEWRITE SENSE EIGHT CHARACTERS	EXIT/ENTRY SENSE LIBRARY TAPE SENSE FULL MONITOR CONTROL SENSE STACKED-JOB MEDIUM SENSE PREVIOUS ASSIGNMENT NUMBER TO ACCUMULATOR SEARCH FOR FREE TAPE SEARCH FOR FREE TAPE SEARCH FOR FREE TAPE EXIT	• EXIT/ENTRY • SENSE CARD REFERENCE
EXF7(21B) SAL(2+2) SAL(2+2) SLJ(L+3) SLJ(L+3) STA(T) EXF7(21B) LDQ(N) LDQ(N) STA(T)	AND/OR SENSE ALL AJP(L+15) SLJ(L+2) SLJ(L+3) SLJ(L+3) SLJ(L+3) SLJ(L+2) SLJ(L+2) SLJ(L+2) SLJ(L+2) SLJ(L+2) SLJ(L+2) SLJ(L+3) SLJ(L) SLJ(L)	STA(15 WT) INA(-2020B) INA(63B)
SLJ(N) SAL(L+5) ENA(T+1) EXF7(11141B) ENA(57B) ENI(7) QLS(6) AJP(7GEX) ENI(0) IJP1(L-4) SLJ(L-6) EXF(62560B)	SLJ(N) EQS(1) SLJ(N) EQS(2N) SSK(3M) EQS(2M) EQS(2M) EQS(2M) LDC(C+8) LDC(C+8) LDC(C+8) LDC(C+8) LDC(C+8) EXF7(7) EXF7(7) EXF7(7) EXF7(118) EXF7(118) EXF7(118) EXF7(118) EXF7(118)	D BINARY RECORD SLJ(N) EXF(635118) AJP1(L+1)
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GET NUMERIC DESIGNATOR SENSE NO MEDIUM REFERENCE ENDFILE BLOCK TO BUFFER	EXIT SENDRY REFERENCE SEND MEMORY RECORD	EXIT SENSE TAPE REFERENCE READ TAPE RECORD		EXIT SENSE CARD REFERENCE	. READ BINARY CARD GROUP	READ CARD LOOP ASSEMBLE EXTRA BITS	SENSE FOR MINUS ZERD	LOOP GET CHECK SUM	CHECK FOR CORRECT READ TROUBLE EXIT
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NA (20)	DA CRIT	DAPPLAX ONCLAN	NAU TO	LJ4(1) NA(1) UP2(L	JP2(51 NA(R) AU(L+2	NNCXX NNCXX NNCXX NNCXX	DAICR DLCR7 JPICL JPCL+	STAI(R) INII(1) RAD(L-7) AUPI(L-8) EXF(708)	L S C C C C C C C C C C C C C C C C C C

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• SENSE FOR ACTION TO TAKE • ERROR EXIT		• EXIT/ENTRY • ARGUMENTS	. CLEAR SIMULATION LOCATIONS . SENSE SWITCH SELECTION	. CLEAR ARGUMENTS . EXIT		• EXIT/ENTRY • CONTROL MEDIUM • CONTROL STATEMENT OUTPUT MEDIUM • ERROR OUTPUT MEDIUM		ENTRY STACKED-JOB MEDIUM LISTABLE-OUTPUT MEDIUM COMPILE-MODE INDICATOR JOB-TIME LIMIT PUNCH-CARD MEDIUM SOURCE-LANGUAGE INDICATOR INTERMEDIATE-LANGUAGE INDICATOR SENSE RECOVERY INDICATOR BACKSPACE STACKED-JOB MEDIUM REWIND LISTABLE-OUTPUT MEDIUM
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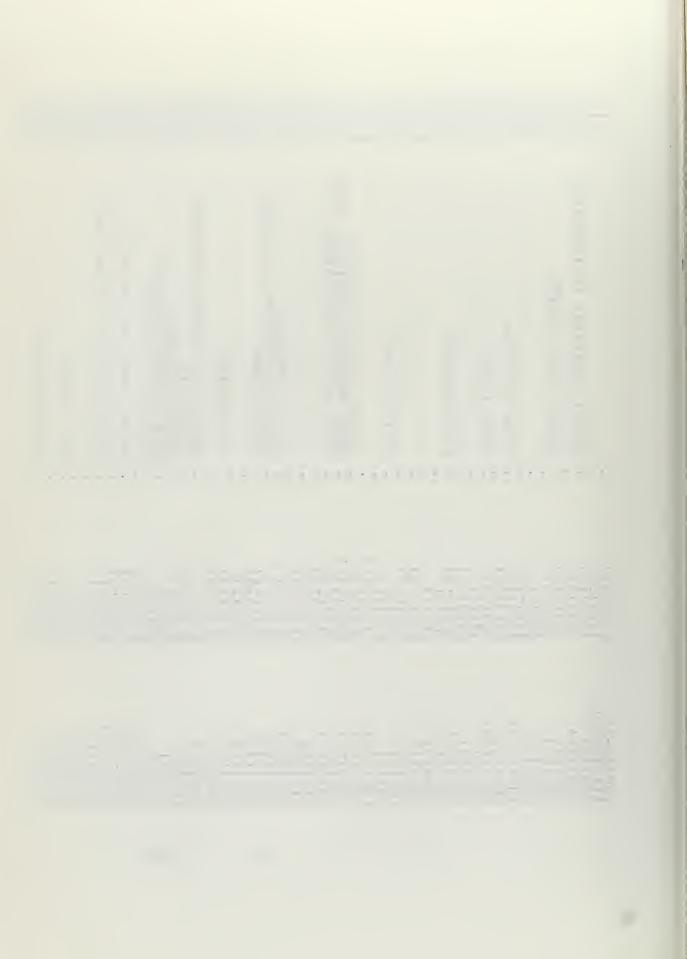
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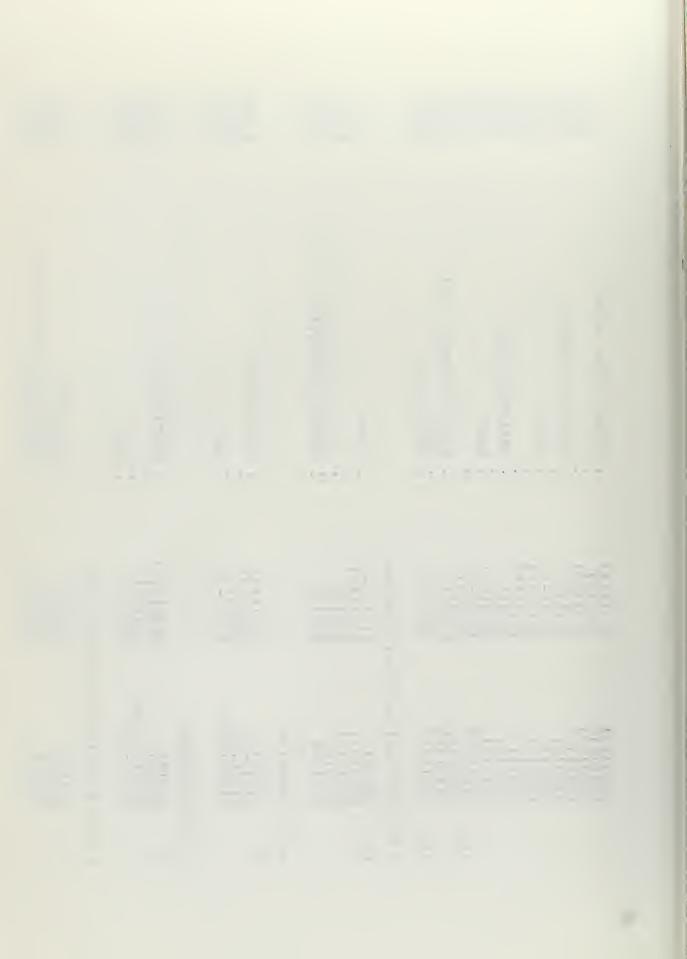
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APPENDIX - IV -



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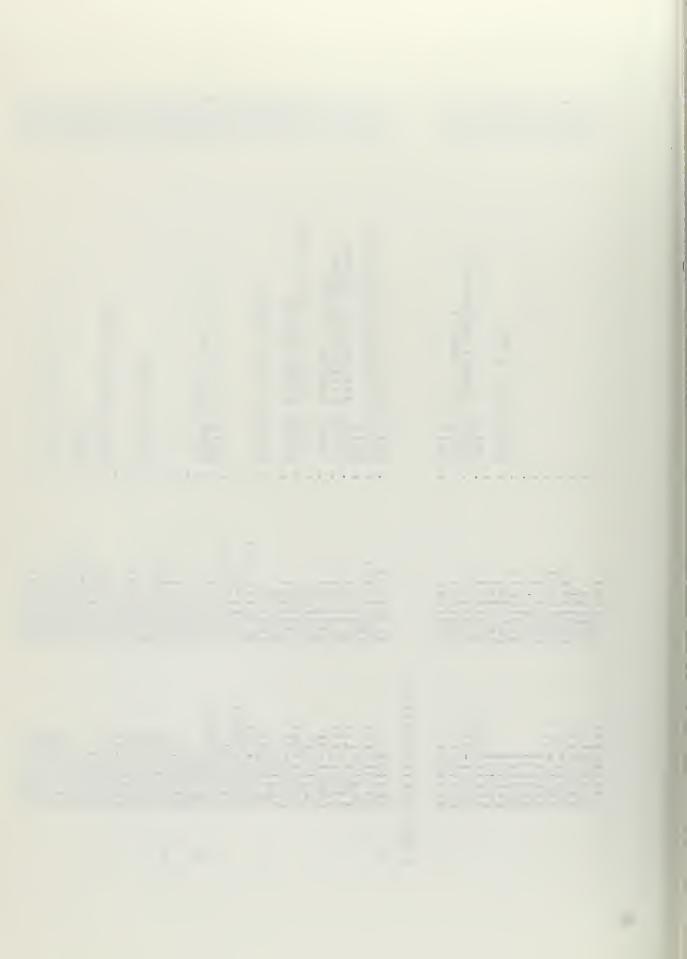
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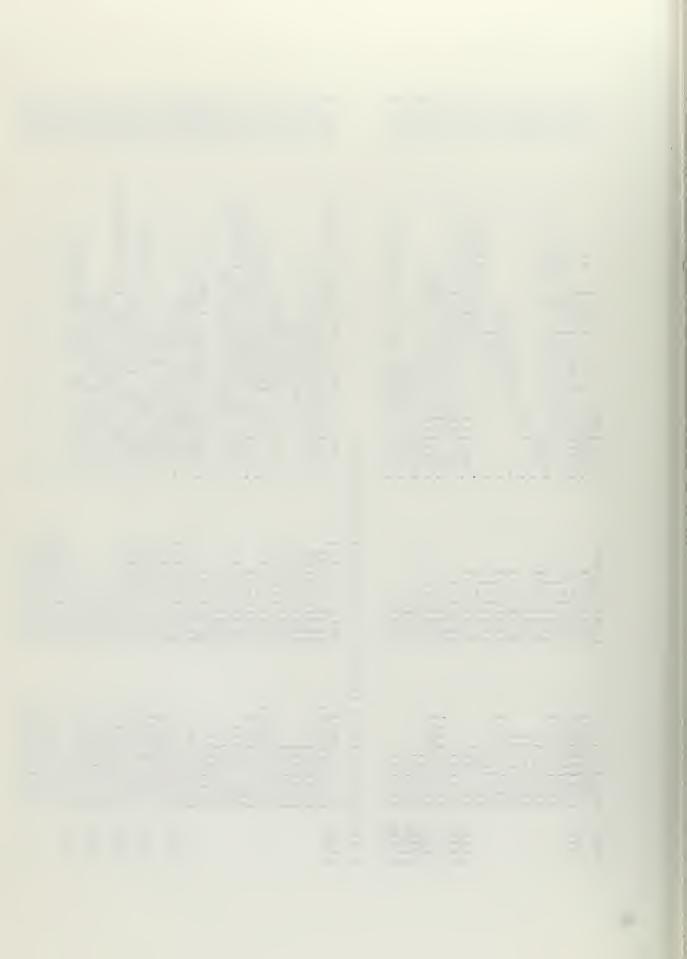
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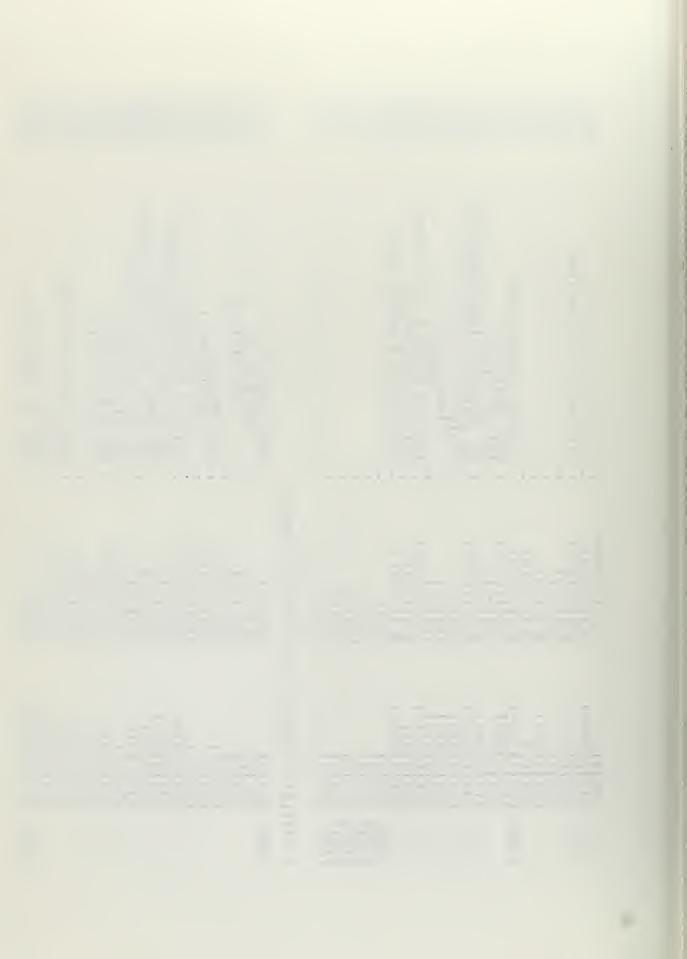
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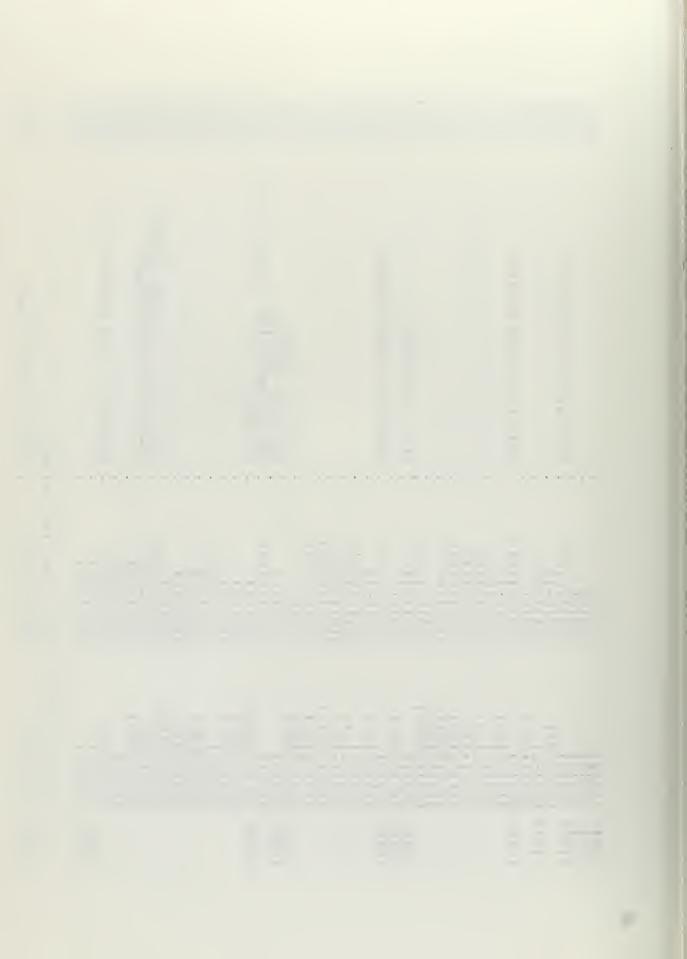
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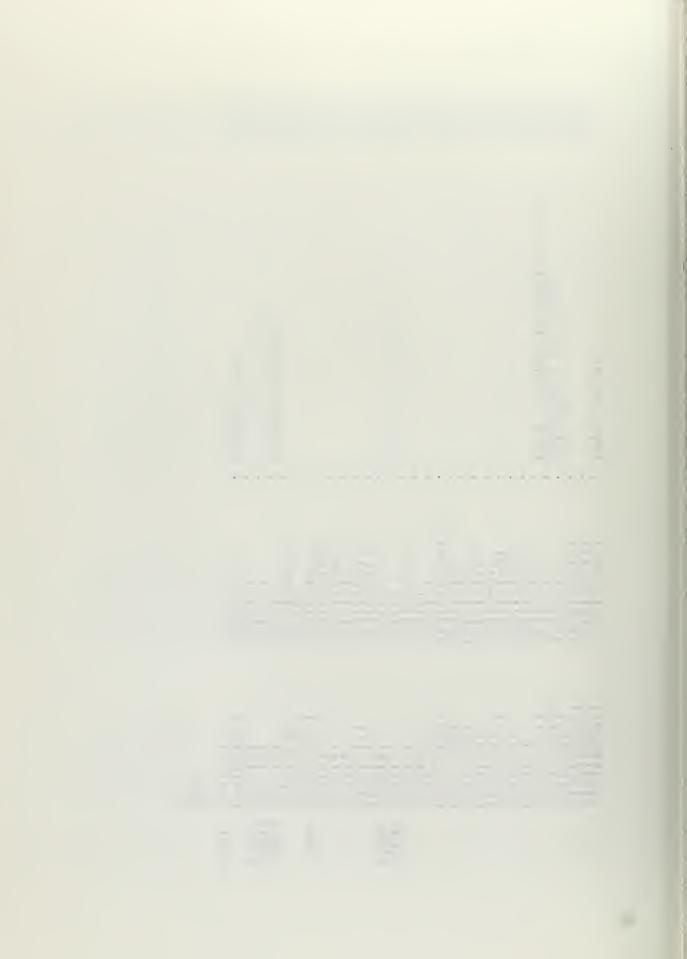
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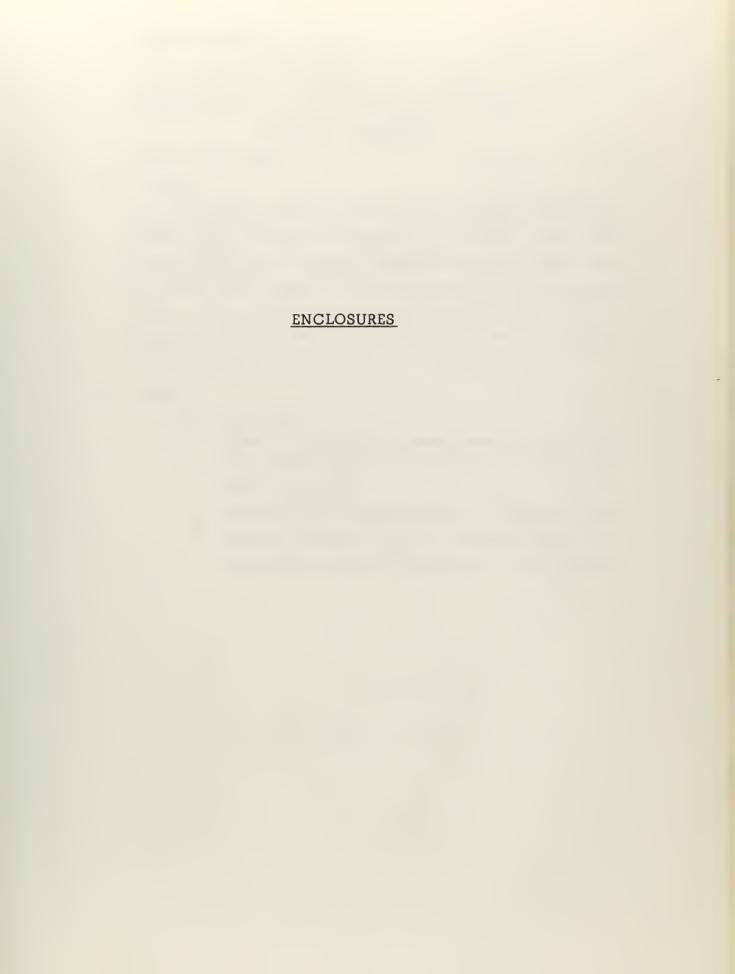
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### ENCLOSURE 1

#### A. IDENTIFICATION

TITLE: 160 Grafplot Routine

PROGRAMMERS: R.L. HOGG / D.C. GLOVER

ORGANIZATION: U.S. Naval Postgraduate School

Monterey, California

DATE: 1 April 1963

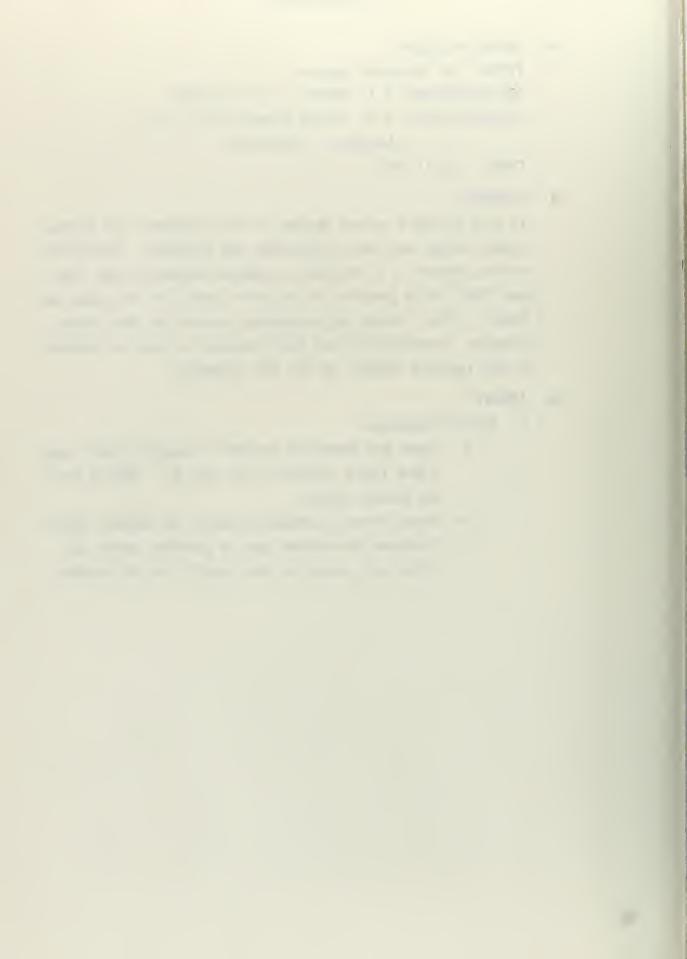
#### B. PURPOSE

To plot multiple curved graphs on the CalComp 165 plotter. Graph titling and axes annotation are provided. The input to the routine is a specially prepared magnetic tape, see the CDC 160-A program of the same name for the input tape format. This routine is a truncated version of the 160-A program, interpolation has been deleted in order to operate in the reduced memory of the 160 computer.

#### C. USAGE

#### 1. Normal Operation

- a. Load the specially prepared magnetic tape input (See 160-A write-up) on unit #1. Select unit for Binary parity.
- b. Load bi-octal grafplot program at address 0000.
- c. Position the plotter pen at position where the lower left corner of the graph is to be plotted.



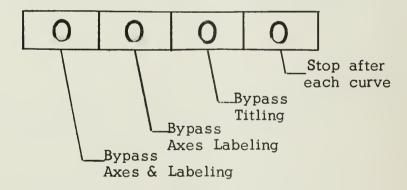
#### d. Starting Addresses

| Location | Contents of "A"              | Results                                                   |  |  |  |  |
|----------|------------------------------|-----------------------------------------------------------|--|--|--|--|
| 0000     | # of graphs to<br>be plotted |                                                           |  |  |  |  |
| 0001     |                              | Skip to next graph.                                       |  |  |  |  |
| 0002     |                              | Backspace to beginning of current graph.                  |  |  |  |  |
| 0003     |                              | Back-up one graph.                                        |  |  |  |  |
| 0004     |                              | Same as a 0000 start.                                     |  |  |  |  |
| 0010     |                              | Rewind tape to Load Pt.                                   |  |  |  |  |
| 0040     | Graph # in A                 | Skips forward N-1 graphs, into position to plot graph #N. |  |  |  |  |

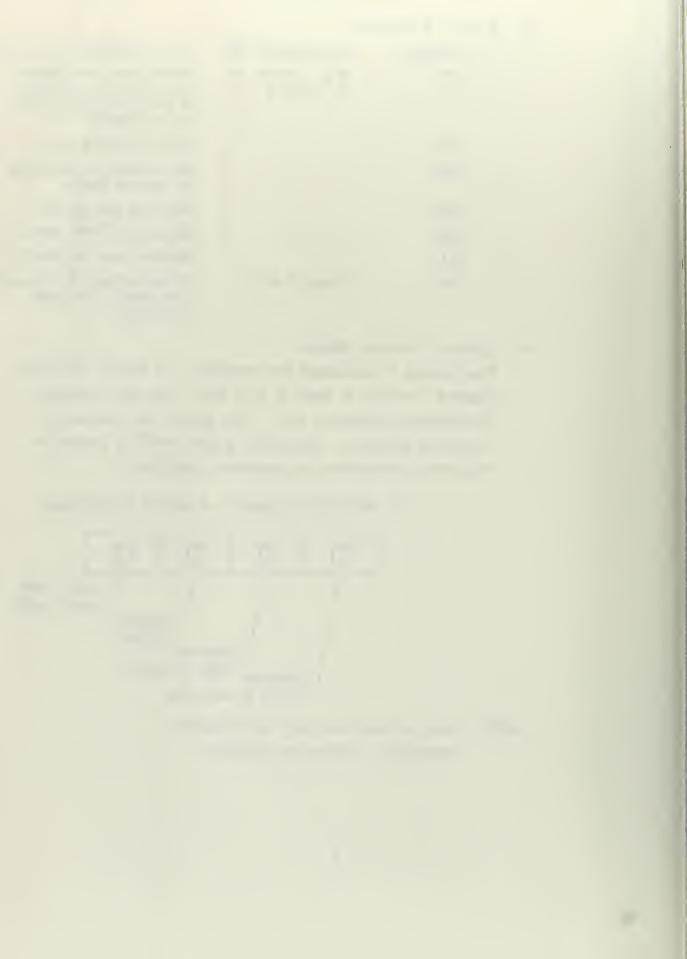
#### e. Optional Running Modes

Four modes of operation are provided. To select the mode desired, execute a start at cell 0020 with the following "A" register arguments set. This primes the routine for the mode selected. Remaining graphs will be plotted in this mode, operations as previously described.

"A" REGISTER FORMAT for MODE SELECTION



NOTE: Entry of any non-zero octal number, constitutes setting an argument.



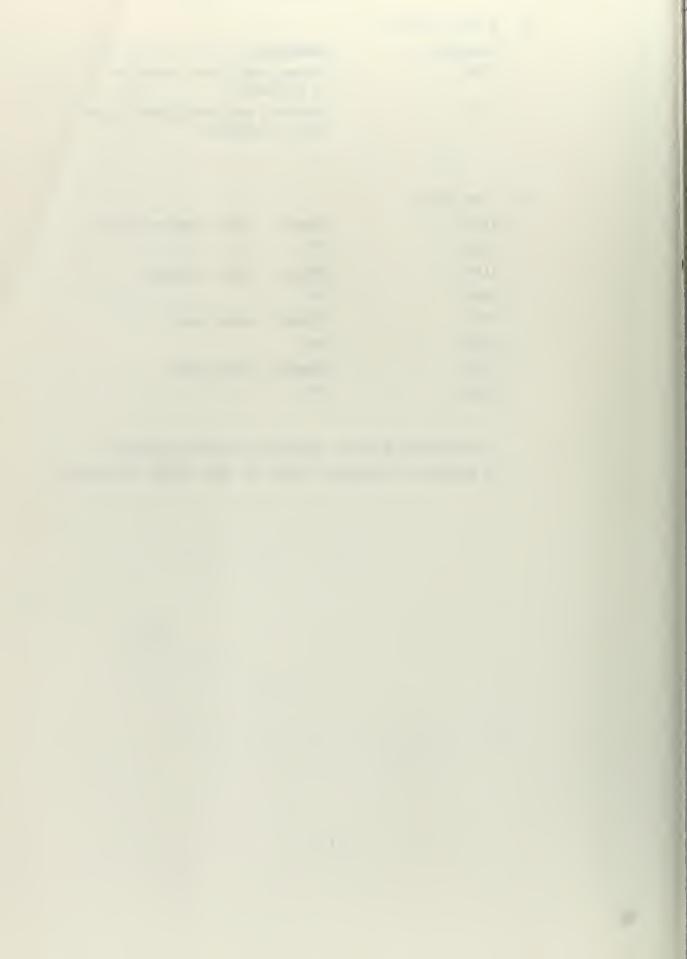
# f. Normal Stops

| Location | Situation                                       |
|----------|-------------------------------------------------|
| 0004     | Normal halt after operation is completed        |
| 1157     | Optional halt after each curve. Run to continue |

| g. | Error Stops |                               |
|----|-------------|-------------------------------|
|    | 0130        | *Parity - Title location data |
|    | 0135        | **                            |
|    | 0173        | *Parity - Title character     |
|    | 0200        | **                            |
|    | 0373        | *Parity - Axed data           |
|    | 0400        | **                            |
|    | 1125        | *Parity - Curve data          |
|    | 1163        | **                            |

<sup>\*</sup> Re-Select Start to continue questionable plot.

<sup>\*\*</sup> Unable to Continue / Skip to next graph to proceed.



DATA CENTERS IDENT: \*BOOL

#### ENCLOSURE 2

TITLE: 160-A Graph Plot Program

DATA CENTERS IDENT: \*B001.

PROGRAMMERS: Maurice D. Weir, Milton Spritzer, D. W. McIlhenny,

Harry Farnsworth

ORGANIZATION: Fleet Numerical Weather Facility, Monterey, California

DATE: 15 August 1962

IDENTIFICATION

REVISED: 4 February 1963, by R. Hogg and D. Glover

#### B. PURPOSE

To plot N curves on the CONTROL DATA 165 Plotter, complete with titling information and annotated axes, from a specially prepared magnetic tape. SEE TAPE FORMAT.

#### C. USAGE

### 1. Computer Operational Procedure

#### a. Normal operation:

- 1) Specially prepared magnetic tape on Unit #1. (SEE TAPE FORMAT)
- 2) Load bi-octal tape at location 0, bank 0. Set direct bank equal to zero.
- 3) Position the plotter pen such that the cross-hairs line up in the following INITIAL POSITION: LEFT most VERTICAL LINE and one of the HALF-INCH HORIZONTAL LINES on the graph paper.

CAUTION: User should indicate this POSITION in relation to a previously plotted graph. This prevents the forthcoming graph from being written over a previously plotted one.

### 4) Starting Address

| Location | Contents of A                | Result                                                                                         |
|----------|------------------------------|------------------------------------------------------------------------------------------------|
| 0000 .   | No. of graphs to be plotted. | Reads tape and plots number of graphs called for. If A = 0, tape will be completely processed. |

| Location | Contents of A | Result                                   |
|----------|---------------|------------------------------------------|
| 0001     |               | Skip to next file.                       |
| 0002     |               | Backspace to beginning of current graph. |
| 0003     |               | Back up one complete graph.              |
| 0010     |               | Rewind tape to load point.               |
| 0040     | Graph No. N   | Skip N-1 graphs, and stop                |

NOTE: Normal halt for above operations is location 4.

- 5) Plotter pen will position itself, draw and annotate the horizontal and vertical axes. Pen will finish by driving back such that the cross-hairs are now lined up with the INTERSECTION of the HORIZONTAL and VERTICAL AXES just drawn.
- 6) Plotter will plot N curves with their identification (if any). Pen will finish by driving back to the INTERSECTION of the HORIZONTAL and VERTICAL AXES.

## 7) Normal Stop

(P) = 0004 - Normal halt for all options.

## 8) Error Stops

- the magnetic tape, have two options. These options are:
  - i) RUN for questionalbe plot, or
  - ii) SET selective jump switch #2 and RUN. This will result in by-passing that particular section of the program (e.g., titling, annotation of axes, or curve).

The error stops are:

P = 0135 - Parity error in title locations

P = 0176 - Parity error in titling data

P = 0401 - Parity error in axes data

P = 1144 - Parity error in curve data

b) The following error stops, which occur during the read from the magnetic tape, have <u>no</u> options. If any occur, operator should check to make certain magnetic tape unit is on unit #1, tape is at load point, tape is ready, 163-2 units are on. Then set (P) according to step 4).

The error stops in this category are:

P = 0142 - titling location

P = 0203 - titling data

P = 0406 - Axes data

P = 1200 - curve data

f = 1103 - error in number of interpolations. RUN.

#### b. Operational variations:

The Graph Plot program contains some special operational procedures which allow for variations in the graph by altering the Normal operation.

## 1) Option to by-pass titling:

After the plotter pen has been positioned in the previously defined INITIAL POSITION, SET selective jump switch #2. Set (P) according to step a.4) and RUN. Titles will be read from magnetic tape but not plotted. Program will make NORMAL STOP P = 0361, and pen will not have moved.

# 2) Option to by-pass axes annotation:

With plotter pen at AXES INTERSECTION and at SPECIAL STOP P = 0361, SET selective jump switch #2 and RUN (do not clear). Axes data will be read from magnetic tape but not plotted. Program will make NORMAL STOP P = 1051, and pen will not have moved.

# 3) Option to PLOT - one-curve-STOP:

With plotter pen at AXES INTERSECTION and at SPECIAL STOP P = 1051, SET selective stop switch #1 and RUN. After curve is plotted, pen will drive back to AXES INTERSECTION, and program will make SPECIAL STOP P = 1174 before the next curve record is read in. Pen-ink may now be changed for next curve, etc. RUN to read in and plot next curve.



## 4) Option to by-pass one curve at a time:

At SPECIAL STOP P = 1051, SET selective jump switch #2 and RUN. Curve data vill be read in, and program will make SPECIAL STOP P = 1065. If selective jump switch # 2 remains set when RUN is set, next curve will be read in, and program will again make SPECIAL STOP P = 1065. If selective jump switch # 2 is not set when RUN is set, next curve will be read in and plotted, etc.

7 1136 6

## 2. Space Requirements

- a. Program: 0 4137 in Bank zero.
- b. Curve data and interpolation: 100 7777 in Bank one.

#### 3: Temporary Storage

Locations 50 - 77 in Bank zero.

#### 4. Tape Mountings

Magnetic tape must be read from unit # 1.

## 5. Caution to Users

Do not step through program. Read write-up carefully before using the Graph Plot Program.

#### D. TAPE FORMAT

Each magnetic tape to be used by this program must have one or more records (as indicated) in each of the following categories:

I Titling data - multiple records

II Axes data - one record

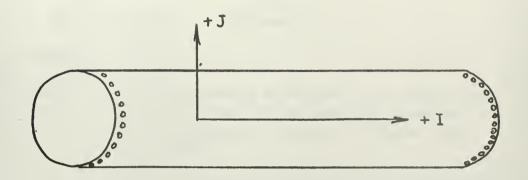
III Curve data - multiple records

IV End of File.

These records <u>must</u> be on the magnetic tape in the <u>order</u> defined above and in the format to be specified below.

. .

## AXES DEFINED AS FOLLOWS:



- I = horizontal axis
- J = vertical axis



## I Titling data

### 1. Record 0

- a. 12 bit binary mode
- b. 4 160-A words (i.e., 1 1604 word)

#### c. Format:

word 0

I distance of initial pt. of first title from the INITIAL POSITION, given as a signed  $\triangle$  I movement in inches times  $100_{\rm d}^{}.$ 

word 1
(J<sub>T</sub>)

J distance of initial pt. of first title from the INITIAL POSITION, given as a signed  $\triangle$  J movement in inches times  $100_{\rm d}$ .

word 2

Orientation of titles defined as follows:

0004 FNWF

0002 JMNJ

0003

Z E e given

word 3

Number of lines in title given as a 12 bit integer. (OCTAL)

# - 2. Records 1 to T

- a. BCD characters in 6-bit binary mode.
- b. Maximum length of 120 d characters where 119 d is number of characters to be plotted.

## c. Format:



character 1 Title line in BCD. Not necessary to fill out this line

character 119

## II Axes data

- 1 record in 12 bit binary mode
- 20 160-A-words
- c. Format:

| word,0 | T distance of initial point of horizontal axis |
|--------|------------------------------------------------|
| (LH)   | from the INITIAL POSITION, given as a signed   |
|        | △I movement in inches times 100,.              |

| word 1            | J distance of initial point of horizontal axis |
|-------------------|------------------------------------------------|
| (J <sub>H</sub> ) | from the INITIAL POSITION, given as a signed   |
| n                 | △J movement in inches times 100 <sub>d</sub> . |

| word 2            | Length of the horizontal axis given as a signed                                                    |
|-------------------|----------------------------------------------------------------------------------------------------|
| (L <sub>H</sub> ) | $\triangle I$ movement from where the axis begins in inches times $100_{\mbox{\scriptsize d}}^{}.$ |

| I distance | of initial point of first horizontal ax     | is |
|------------|---------------------------------------------|----|
| label from | the INITIAL POSITION, given as a            |    |
| signed △I  | movement in inches times 100 <sub>d</sub> . |    |

| J distance           | of i | nitial | point  | of   | first  | horizon | ta1 |
|----------------------|------|--------|--------|------|--------|---------|-----|
| axis label           | from | the I  | NITIAL | POS  | ITION, | given   | as  |
| a signed $\triangle$ | J mo | vement | in ind | ches | times  | 100     |     |

| I  | d: | İstance | bet | tween | hori | zor | ntal | 1ab | els,  | given              |
|----|----|---------|-----|-------|------|-----|------|-----|-------|--------------------|
| as | а  | signed  | ΔΙ  | mover | nent | in  | inch | es  | times | 100 <sub>d</sub> . |

| First value which is to be plotted for the hori- |
|--------------------------------------------------|
| zontal axis labeling. This is a signed 12 bit    |
| integer which will be converted to BCD. Its      |
| maximum value cannot exceed +999 <sub>d</sub> .  |

| Value of th | e∆I dist | ance | between  | horizontal   |
|-------------|----------|------|----------|--------------|
| axis labels | given as | a si | igned 12 | bit integer. |

Number of horizontal axis labels to be plotted. This is always a positive 12 bit integer.

word 3 (I<sub>HL</sub>)

word 4 (J<sub>HL</sub>)

word 5 ( I<sub>HL</sub>)

word 6 (V<sub>H</sub>)

word 7 ( V<sub>H</sub>)

word 8 ~ (NH)

| word 9<br>(S <sub>H</sub> )   | Upper six bits: Size of letters in horizontal axis labeling.                                                                 |
|-------------------------------|------------------------------------------------------------------------------------------------------------------------------|
| (0 <sub>H</sub> )             | Lower six bits: Orientation of horizontal axis labels. Orientation previously defined.                                       |
| word 10 (I <sub>V</sub> )     | I distance of initial point of vertical axis from the INITIAL POSITION, given as a signed AI movement in inches times 100 d. |
| word 11<br>(J <sub>ý</sub> )  | Vertical axis analogy to word 1.                                                                                             |
| word 12 (L <sub>V</sub> )     | Vertical axis analogy to word 2.                                                                                             |
| word 13 (I <sub>VL</sub> )    | Vertical axis analogy to word 3.                                                                                             |
| word 14 (J <sub>VL</sub> )    | Vertical axis analogy to word 4                                                                                              |
| word 15 ( J <sub>VL</sub> )   | Vertical axis analogy to word 5                                                                                              |
| word 16 (V <sub>V</sub> )     | Vertical axis analogy to word 6.                                                                                             |
| word 17<br>( V <sub>V</sub> ) | Vertical axis analogy to word 7.                                                                                             |
| word 18<br>(N <sub>V</sub> )  | Vertical axis analogy to word 8.                                                                                             |
| word 19 (S <sub>V</sub> )     | Upper six bits: Size of letters in vertical axis labeling.                                                                   |
| (0 <sub>V</sub> )             | Lower six bits: Orientation of vertical axis                                                                                 |

## III Curve data

- a. Multiple records in 12 bit binary mode.
- b. m words long where m has maximum value of 36778.

labels.

c. Each I, J must be given as a distance from the INITIAL POSITION, as a signed  $\triangle I$ ,  $\triangle J$  movement in inches times  $100_d$ .



#### d. Format:

| word U   | 0000                                                        |
|----------|-------------------------------------------------------------|
| word 1   | 0000                                                        |
| word 2   | 0000                                                        |
| word 3   | number of interpolations (00 - 07)                          |
| word 4   | I,                                                          |
| word 5   | $J_1^L$                                                     |
| word 6   | I.                                                          |
| word 7   | J <sub>1</sub> J <sub>1</sub> I <sub>2</sub> J <sub>2</sub> |
|          | 2                                                           |
|          |                                                             |
| •        |                                                             |
| word m-5 | 3777 end flag                                               |
| word m-4 | 3777 end flag                                               |
| word m-3 | curve name. 4 BCD characters,                               |
| word m-2 | packed two to a word.                                       |
|          |                                                             |

upper six bits: letter size of curve name lower six bits: orientation of curve name

#### IV End of File

word m-1

#### E. TIMING

Each graph takes 2 - 3 minutes to plot, including titling, annotated axes, and interpolation.

#### F. METHOD

## 1. General

All location points on the graph are interpreted as being relative to the (0, 0) INITIAL POSITION previously defined. All lengths, intervals, etc. must have the appropriate sign according to the definition of the (I, J) axes. Information is plotted as follows: titles, horizontal axis, horizontal axis annotation, vertical axis, vertical axis annotation, and finally the curve(s) (with interpolations, if any). The program uses TAP for reading the magnetic tape input, OVDR for driving to a position with the pen up, LINE for joining given points with the pen down, and LABEL for titling.

# 2. Titles

The initial points from the magnetic tape input are used to position the pen in the desired location on the graph for the first title. The



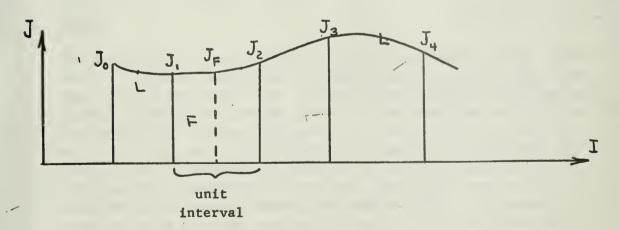
first title is plotted, and if there are additional titles, the program calculates the appropriate spacing between lines according to the orientation and the letter size of the incoming title. The program keeps track of all pen movements so that when the last title is plotted, pen drives back to the (0, 0) INITIAL POSITION.

#### 3. Annotation of Axes

The initial points from the magnetic tape input are used to position the pen in the desired location on the graph for the start of the horizontal axis. The axis is drawn, and then the pen moves into position to begin the first horizontal axis label. This first label is plotted according to its size and orientation; the remaining labels being computed and then plotted at the desired intervals, based upon the initial value, the scaling, and the number of labels desired. At the completion of the horizontal axis annotation, the pen positions itself at the start of the vertical axis. The axis is drawn and labelled as in the horizontal axis annotation. The program keeps track of all pen movements so that when the vertical axis annotation has been completed, pen drives back to the INTERSECTION of the HORIZONTAL and VERTICAL AXES.

### 4. Interpolation

This is a four-point interpolation method based on the Bessel Interpolation Equations.



The interpolation scheme fits the four points to a quadratic curve, computing the interpolated point  $J_{r}$  by the following equation:

$$J_F = J_1 + F (J_2 - J_1) + F (F - 1)$$
  $(J_0 + J_3 - J_2 - J_1)$ 

The program uses F = 1/2.



This interpolation method depends upon equal I intervals. Since it cannot perform an interpolation between the first and last pairs of J values, a linear interpolation is performed at these two positions (marked "L" in the diagram). This linear interpolation occurs at the half-interval of both end pairs, which allows the user to make more than one interpolation by maintaining equality of I intervals.

The number of interpolations X desired must comply with the following inequality:

$$\frac{5\times}{\sqrt{100}}$$

The program has set the maximum number of interpolations as 07.

If the number of interpolations indicated (see TAPE FORMAT, "curve data") exceeds this maximum, program will interpolate 07 times only, and indicate an error in the number of interpolations indicated.

<u>Caution</u>: Because of the necessary storage space for the curve data points, the maximum number of (I, J) points that can be plotted after interpolation is 980<sub>d</sub>.

<u>WARNING</u>: Since the interpolation depends upon <u>equal spacing of</u>
<u>the I intervals</u>, any curve which does not have equally spaced points
<u>will not</u> be properly interpolated. This applies to multiple-valued
functions and asymptotic values.

#### 5. Curves

The first (I, J) curve data point from the magnetic tape input is used to position the pen in the desired location on the graph for the start of the curve plot. Curve is then plotted by joining successive points by a straight line. At the completion of plotting the curve (with the desired number of interpolations, if any), program labels curve (if desired) with indicated orientation and letter size. Program keeps track of all pen movements so that when the curve labelling is completed, pen drives back to the INTERSECTION of the HORIZONTAL and VERTICAL AXES. If another curve is to be plotted, program proceeds in the same manner as for the first curve. When the final curve is plotted, pen will be positioned at the INTERSECTION of the HORIZONTAL and VERTICAL AXES.

Caution: User may not desire a curve label, in which case blanks are indicated on the magnetic tape for the four BCD characters.



(see TAPE FORMAT, "curve data.") Newertheless, an orientation and letter size must still be indicated since they are required by the LABEL subroutine.

FINIS



#### A. IDENTIFICATION

TITLE: 1604 Graph Plotting Subroutine

DATA CENTERS IDENT: \*A002.

PROGRAMMERS: R. L. Hogg and D. C. Glover

ORGANIZATION: Naval Postgraduate School, Monterey, California

DESCRIPTION WRITE-UP: E. A. Campbell, CDC

DATE: 5 March 1963

#### B. PURPOSE

To write data on a magnetic tape for off-line plotting on the CONTROL DATA 165 plotter. The tape format is compatible with the 160-A Graph Plot Program (Data Centers Ident \*B001) which is used to drive the 165 plotter.

## C. USAGE

### 1. Calling Sequence

a. FORTRAN-62

CALL GRAFPLOT (MODCURV, NUMPTS, X, Y, LABEL, INTERPS, SFX, SFY, IXOFFS, IYOFFS, IWIDE, IHIGH, MODE, TITLESIZ, TITLE1, TITLE2, ...., TITLEN)

CALL AUTOGRAF (MODCURV, NUMPTS, X, Y, TITLE1, TITLE2, ...., TITLEN)

#### b. CODAP1

Either: ENA (MODCURV)

ENQ (NUMPTS)

RTJ GRAFPLOT

ZRO X

ZRO Y,

ZRO LABEL

ZRO INTERPS

ZRO SFX

ZRO SFY

ZRO IXOFFS

ZRO IYOFFS

ZRO IWIDE

ZRO IHIGH

ZRO MODE

ZRO TITLESIZ

ZRO TITLE1

ZRO TITLE2

ZRO TITLEN

| Or: |   | ENA | (MODCURV) |
|-----|---|-----|-----------|
|     |   | ENQ | (NUMPTS)  |
|     |   | RTJ | AUTOGRAF  |
|     | + | ZRO | X         |
|     |   | ZRO | Y         |
|     |   | ZRO | TITLE1    |
|     |   |     |           |
|     |   | •   |           |
|     |   | ZRO | TITLEN    |
|     | + | RTJ | ERROR     |

# 2. Input Parameters

| Parameter Name | Value    | Description                         |
|----------------|----------|-------------------------------------|
| *MODCURV       | 0        | First and last curve for this graph |
|                | 1        | First curve of many                 |
|                | 2        | Intermediate curve                  |
|                | 3        | Final curve for this graph          |
| NUMPTS         | 1-900    | Number of points                    |
| X              |          | Location of X coordinates           |
| Y              |          | Location of Y coordinates           |
| LABEL          | 4 BCD    |                                     |
| ·              | Char.    | BCD label for curve                 |
|                | 0        | No label                            |
|                | -0       | Automatic sequencing of curves for  |
|                |          | No. 1-8.                            |
| INTERPS        | 0        | No interpolation between coordinate |
|                |          | points                              |
| 1              | 1-7      | One to 7 interpolations between     |
|                |          | coordinate points                   |
| SFX            | 0        | Program will find best scale factor |
|                | Fl. Pt.  |                                     |
|                | Number . | Scale factor for X **               |
| SFY            | 0        | Program will find best scale factor |
|                | F1. Pt.  | •                                   |
| •              | Number   | Scale factor for Y **               |
| IXOFFS         | 1-10     | Number of inches to offset X axis   |
|                | 0        | No offset                           |
| IYOFFS         | 1-10     | Number of inches to offset Y axis   |
|                | 0        | No offset                           |
| IWIDE          | 1-10     | Length of X axis - inches           |
| IHIGH          | 1-120    | Length of Y axis - inches           |
|                |          |                                     |

<sup>\*</sup>If MODCURV is 2 or 3, then only the first 6 parameters need to be repeated.

\*\*Scale factor = 100/units per inch on plotted output.

| Parameter Name | <u>Value</u> | Description                                                                                                           |
|----------------|--------------|-----------------------------------------------------------------------------------------------------------------------|
| MODE           | 0            | Automatically calculate best axes offset for origin at lower left                                                     |
|                | 1            | Locate origin at center                                                                                               |
|                | 2            | Locate origin at lower left                                                                                           |
|                | 3            | Locate origin at upper left                                                                                           |
|                | 4            | Locate origin at upper right                                                                                          |
|                | 5            | Locate origin at lower right                                                                                          |
| TITLESIZ       | 1-24         | Multiplier for lettering size. Basic size is .l inches.                                                               |
| TITLE1         |              | Location of first title. Title array must be at least 10 words of BCD characters. Fill unused characters with blanks. |
| •              |              |                                                                                                                       |
| TITLEN         |              | Location of Nth title array                                                                                           |

### 3. Space Requirements

1120 decimal locations

#### 6. Error Returns

No error return is used, however, an error return point is skipped in order to be compatible with FORTRAN subroutines.

## 8. Input/Output Tape Mountings

Plot data output on logical 48 through CO-OP Monitor.

## 9. Input/Output Tape Formats

See 160-A Graph Plot Program write-up for details. The basic form is titling information, axes annotation, and curve data with an end of file separating graphs. No special end of tape mark is used to terminate the tape.

#### 13. Cautions to Users

- a. If scale factors are defined, then the appropriate axes offsets should also be defined.
- b. The normal width of the plotter paper is 10 inches. For best results, do not use a horizontal axis length greater than 9 inches.

c. The number of interpolations N required must comply with the following inequality:  $\Delta I/2^n > 1/100$  where  $\Delta I$  is the uniform (equal) increment along the horizontal axis. See reference for further details.

# 14. Equipment Configuration

CO-OP Monitor configuration with at least one output tape available.

## 15. References

This program uses 160-A Graph Plot Program (Data Centers Ident No. \*B001) as a subset to drive the 165 plotter.











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